

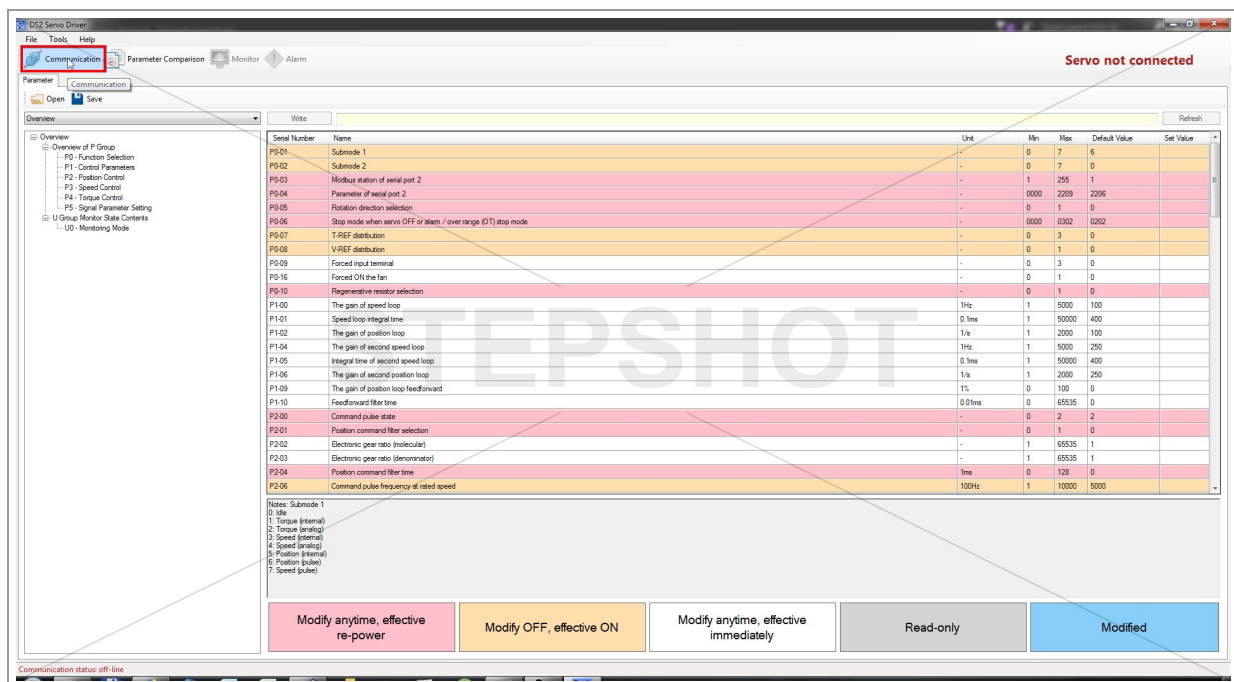
SAH DS2 Servo Driver Software Manual

Igor Filipovic

This is a brief overview of all implemented software features and cases of use. If you have any issues or questions, feel free to contact me: igor@sah.rs

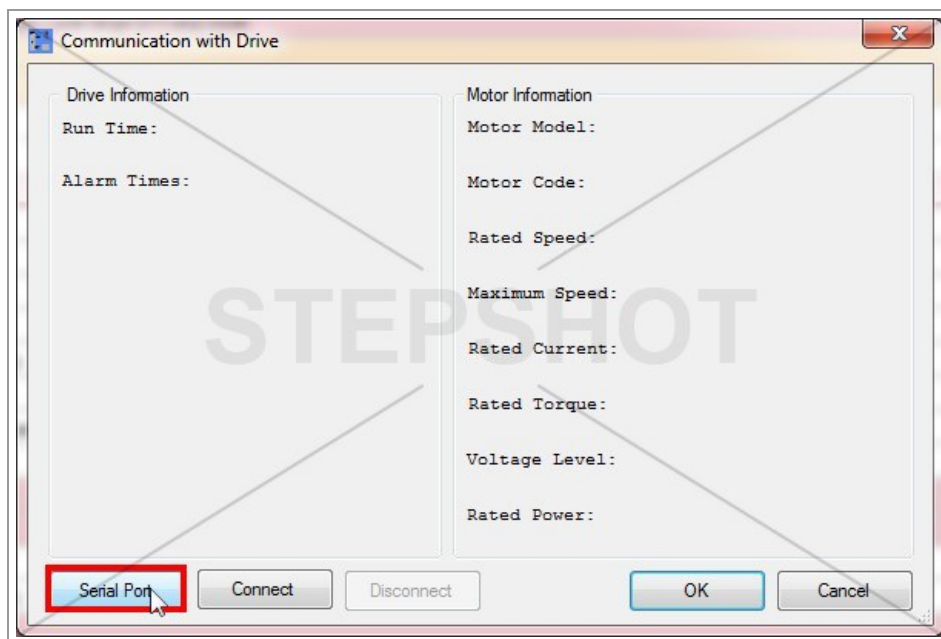
Communication Establishment

Communication Settings

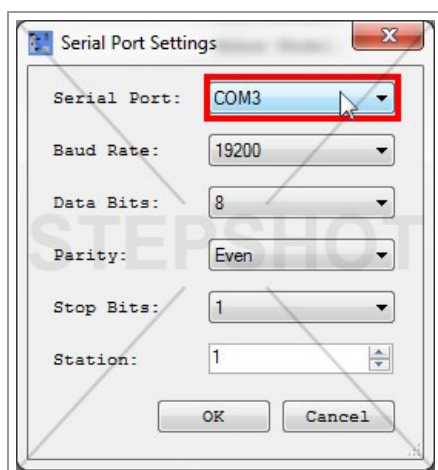


Click on "Communication" button to open the settings for communication establishment.

Serial Port Settings



Click on "Serial Port" button to set the parameters of your communication (serial port number, baud rate, parity, etc.).

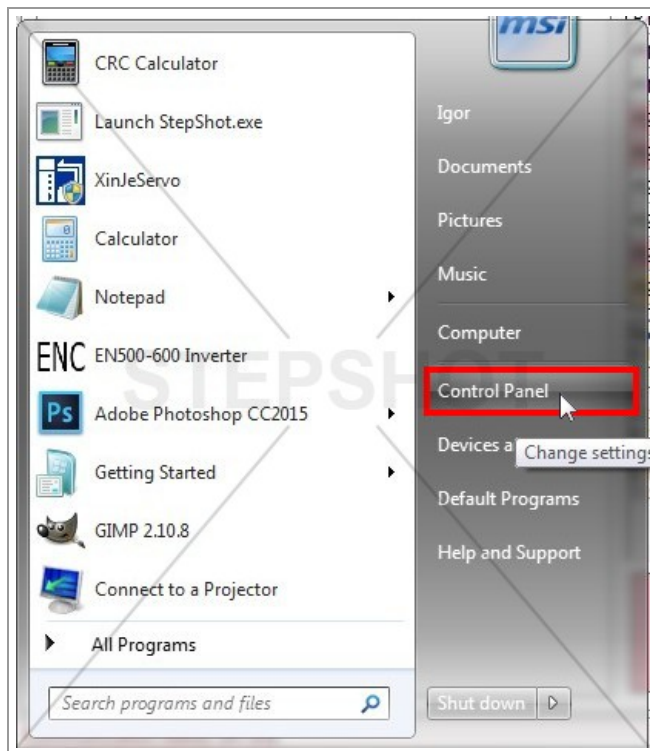


By clicking on "Serial Port" dropdown menu, you'll get the list of all available serial ports on your computer.

To make sure what port is your servo driver connected to, go to Control Panel -> Device Manager -> Ports (COM & LPT) and check for USB-SERIAL CH341A.

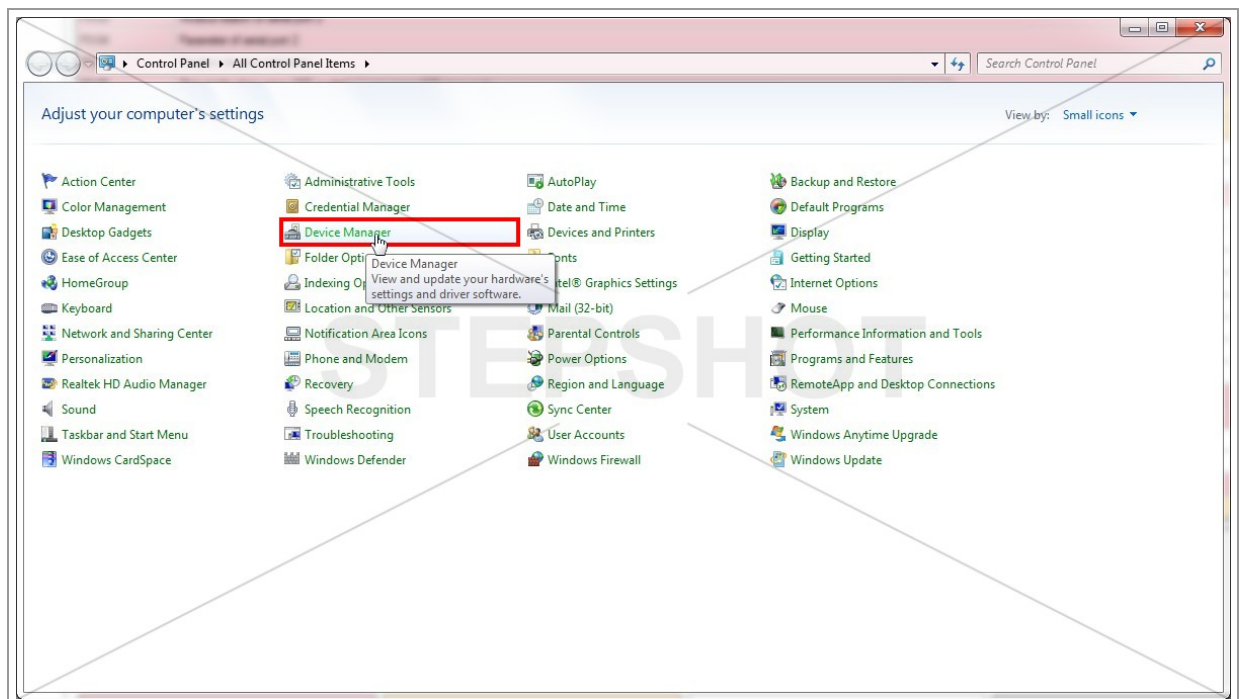
If you're having a problem with this, check next few steps.

Check for Serial Port

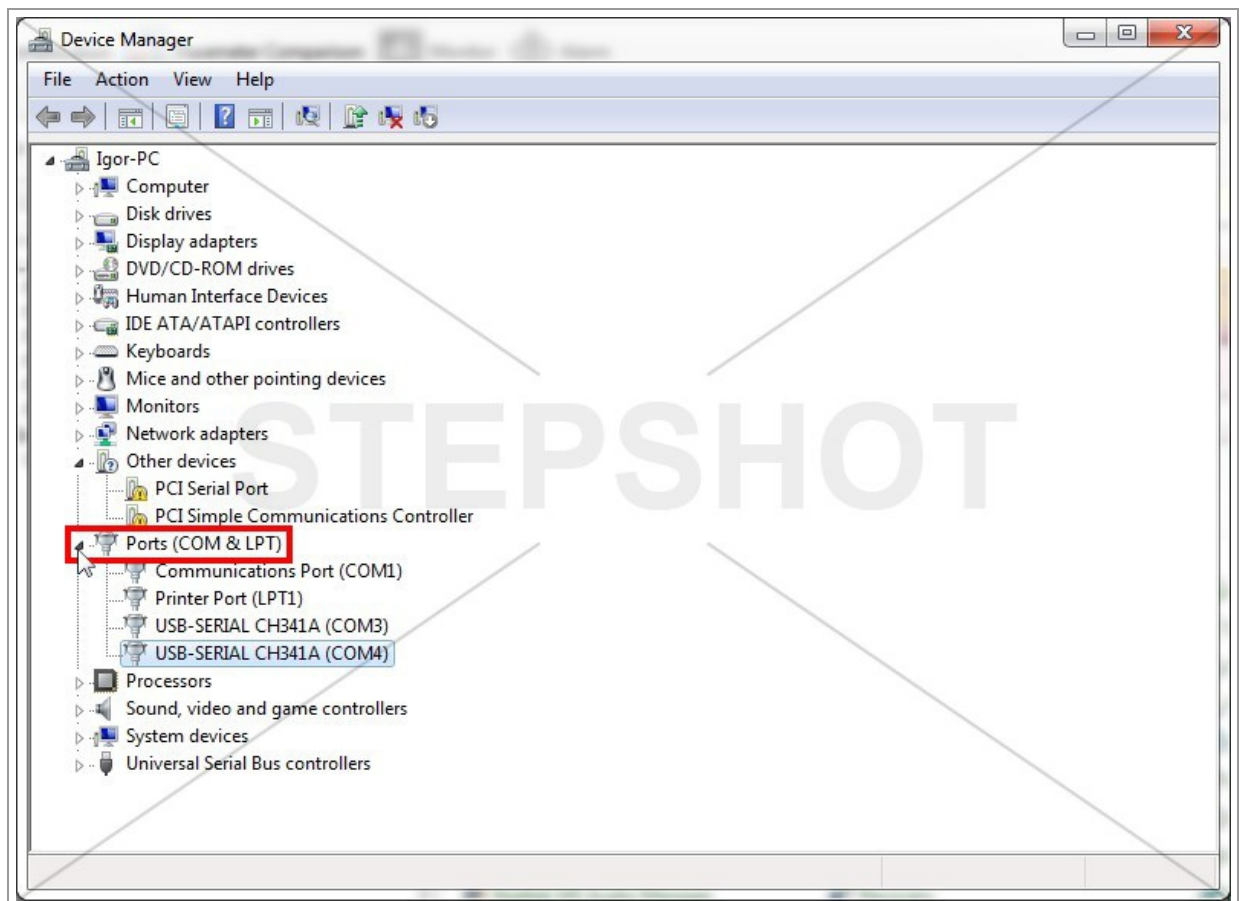


This is the procedure of checking your serial port if you're using Windows 7. It's similar to other Windows platforms.

Click on "Control Panel" button in your Start menu.



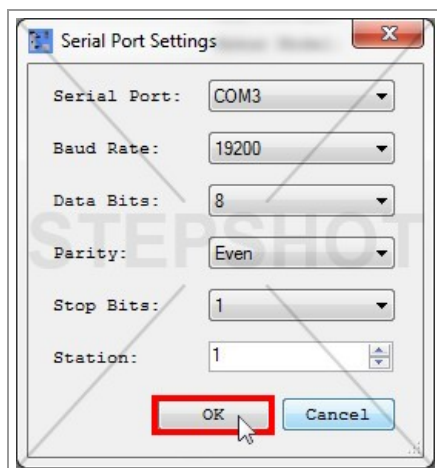
Click on "Device Manager" link in "All Control Panel Items" (if you cannot find it, search for "Device Manager" in search box).



In "Device Manager" menu click on small triangle left to "Ports (COM & LPT)" to expand the all connected ports to your computer.

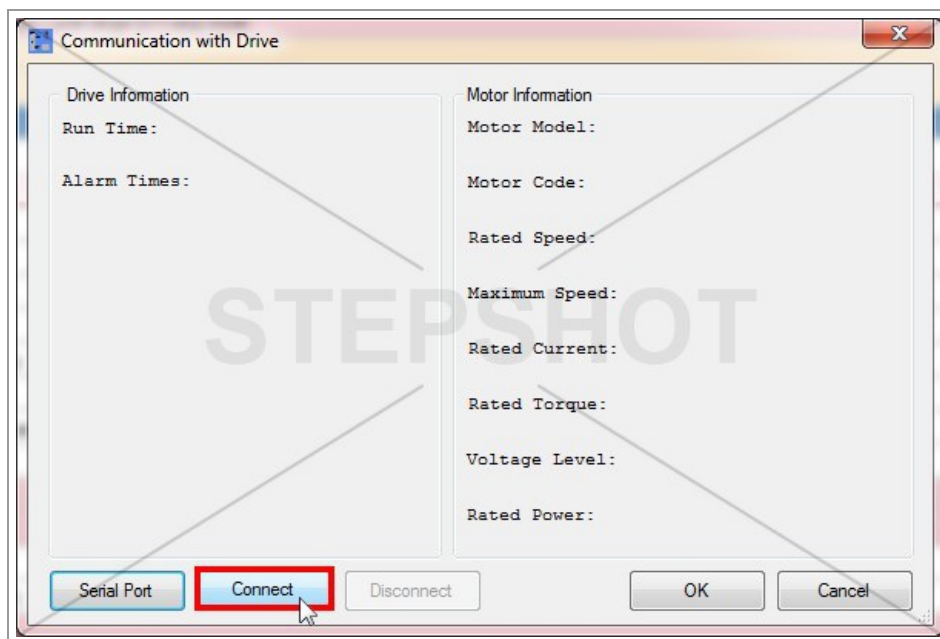
Find "USB-SERIAL CH341A" and notice its label in brackets (COM + number).

Use that label in your serial port selection.

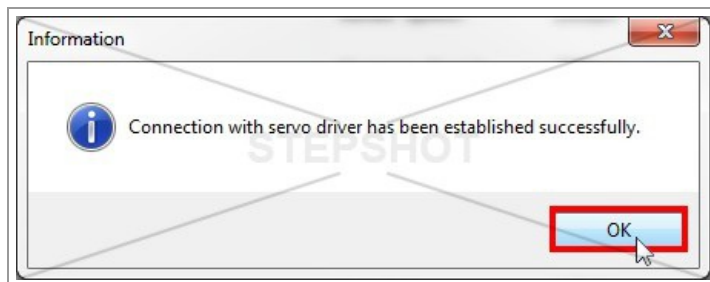


Go back to your "Serial Port Settings", set the other parameters as explained in device manual and click on "OK" button to confirm them.

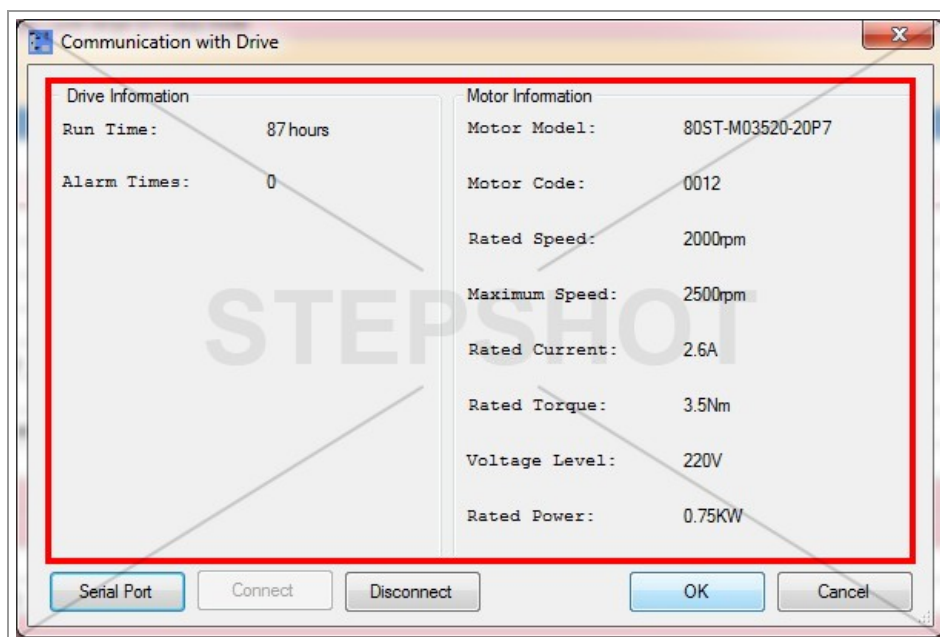
Connect the Servo Driver



Click on "Connect" button in "Communication with Drive" to establish the communication with servo driver.

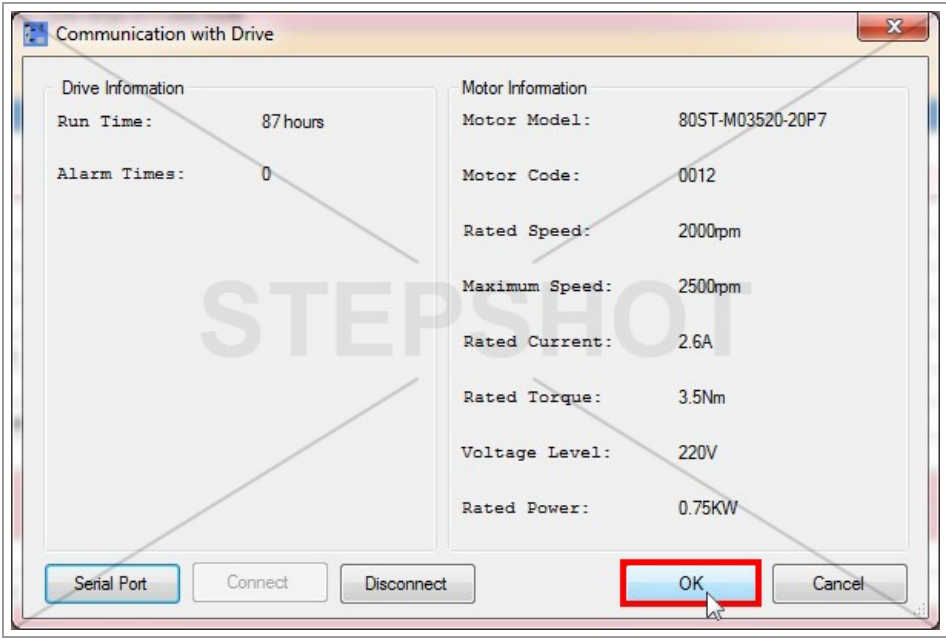


You should get the information about successful communication establishment.

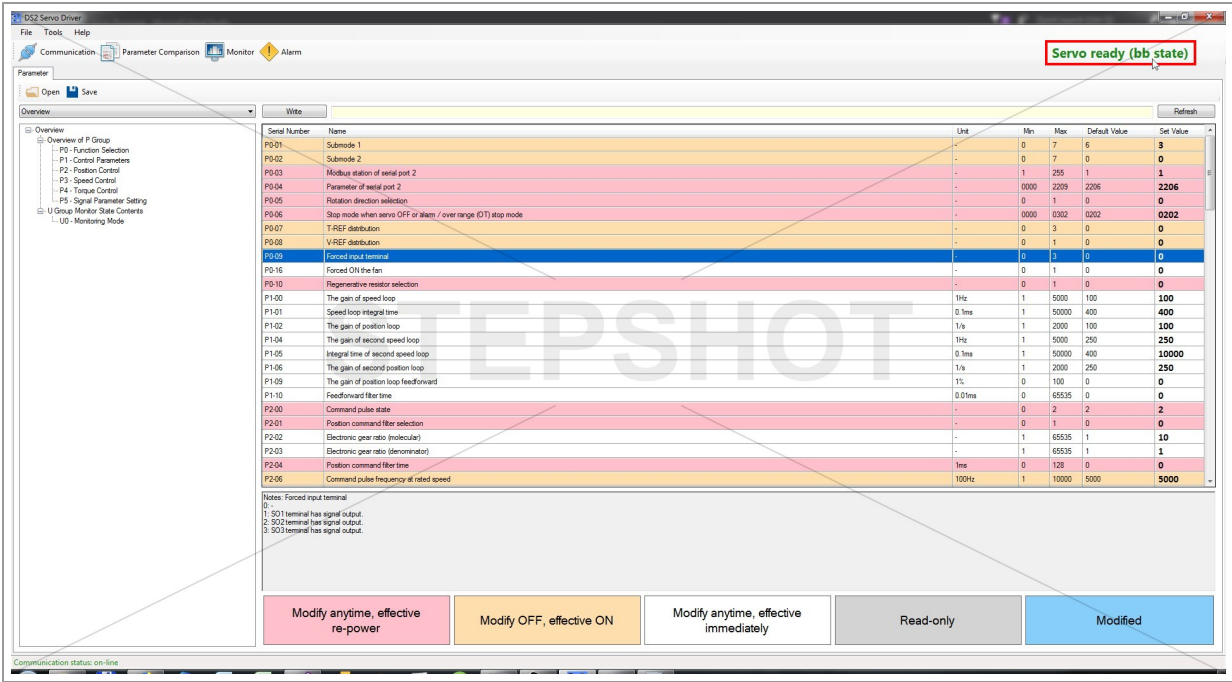
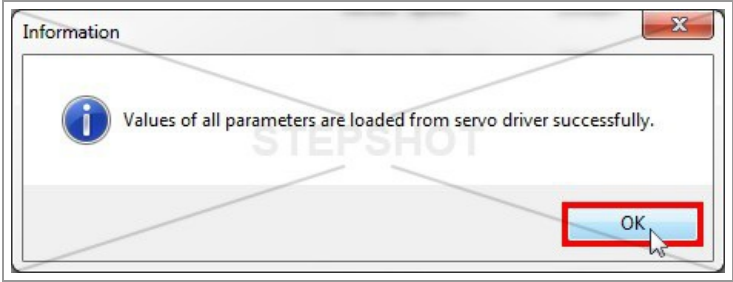


You'll get the essential information about your driver and motor.

Read The Values From Driver

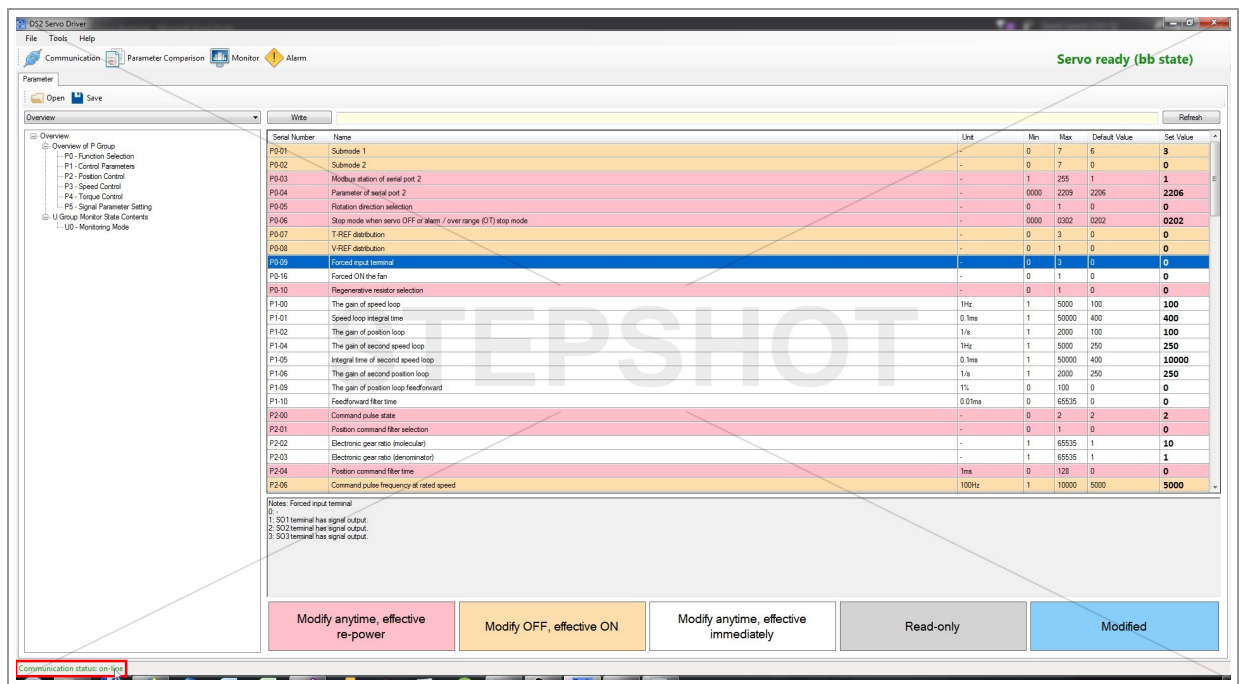


Click on "OK" button in "Communication with Drive" to load the values of all driver parameters.



You'll notice that the servo status indicator is changed from "Servo not connected" to "Servo ready (bb state)".

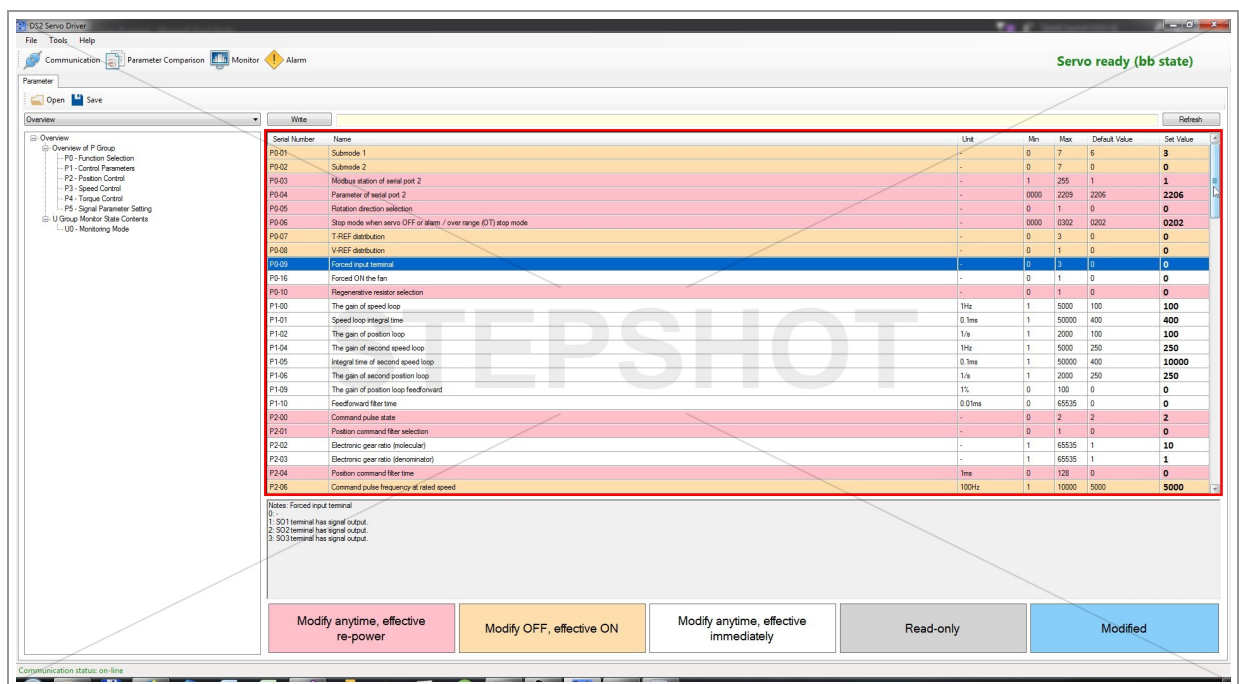
This indicator shows the current state of servo (bb, run, alarm, connected, not connected).



You can also check for the current communication status in the left corner of your status bar (green -> on-line, red -> off-line).

Review of The Main Features

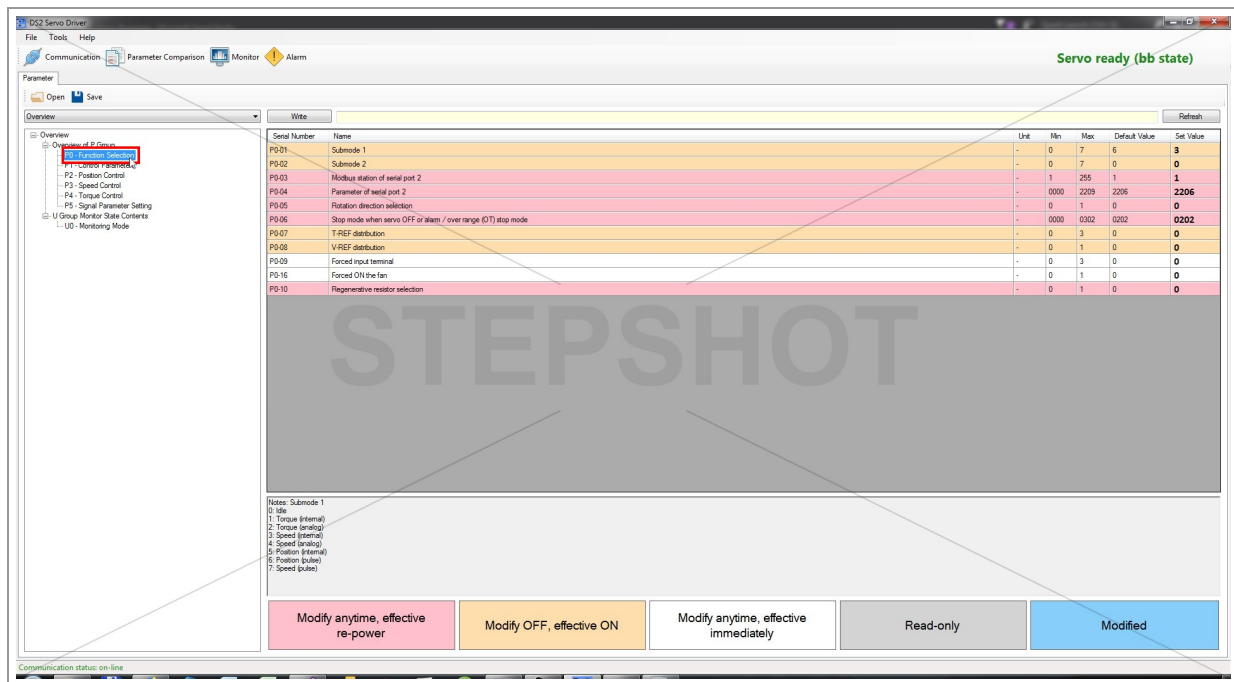
Parameter Table



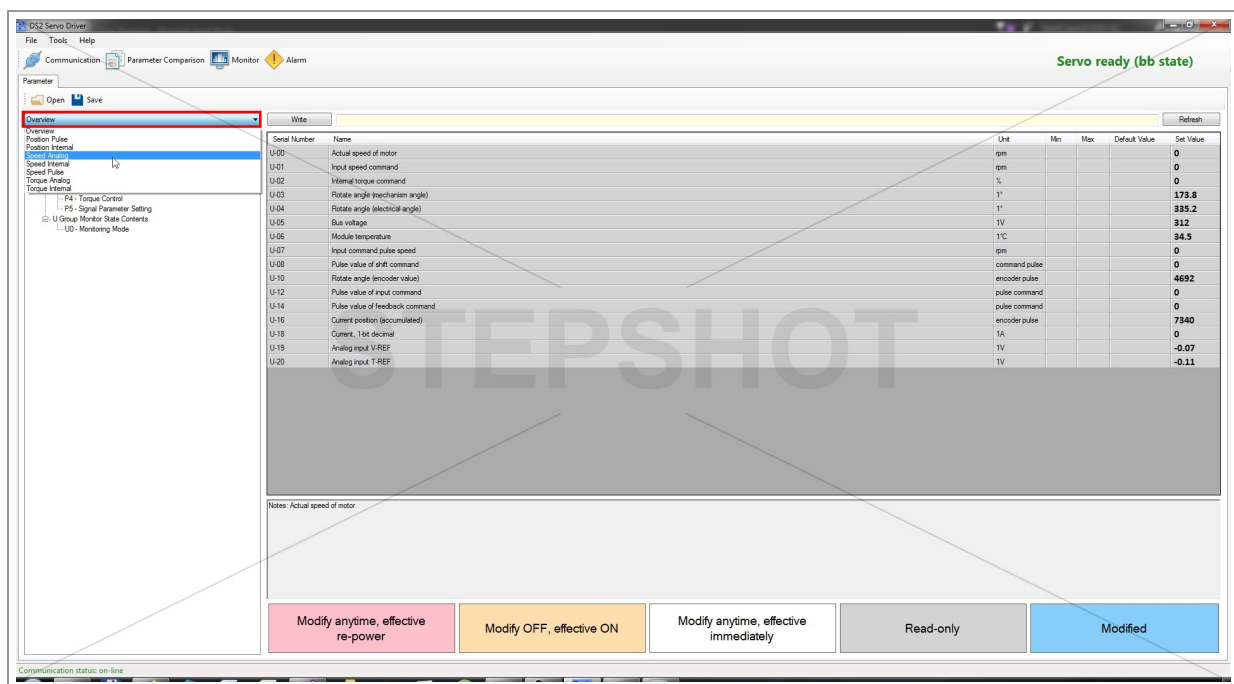
All available parameters are shown in the full table view with their serial number, description, unit, minimum value, maximum value, factory default value and current value read from the servo driver in the moment of establishing communication.

You are able to scroll the table vertically.

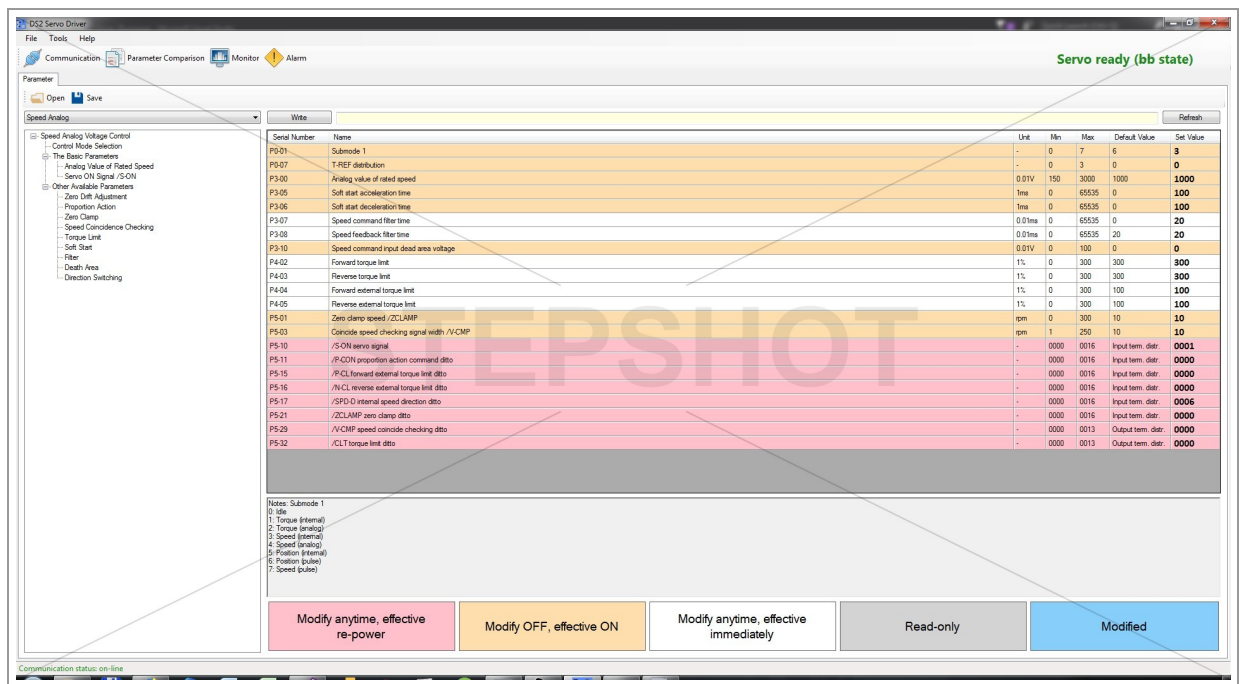
Tree View Selection



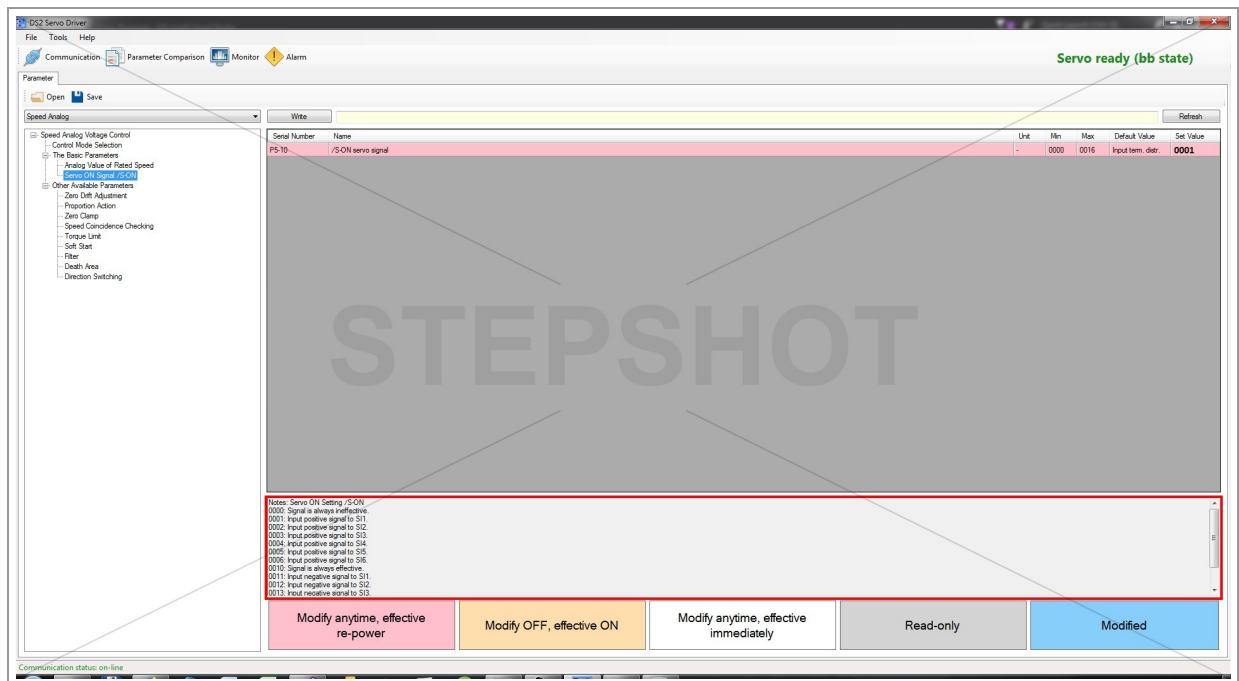
You can shorten the list of parameters in table by clicking the desired group of parameters in the tree view menu.



Also you can select the parameters relevant to certain control mode by choosing it from dropdown menu above the tree list.



Notes



Notes are shown for each parameter, when clicked.

There you can find the more detailed description and the list of possible values with explanation.

Row Color Explanation

DS2 Servo Driver

File Tools Help

Communication Parameter Comparison Monitor Alarm

Servo ready (bb state)

Parameter

Open Save

Write Refresh

Overview

Overview of P Group

- P0 - Function Selection
- P1 - Control Parameters
- P2 - Position Control
- P3 - Speed Control
- P4 - Torque Control
- P5 - Signal Parameter Setting
- U Group Monitor State Contents
 - U0 - Monitoring Mode

Serial Number	Name	Unit	Min	Max	Default Value	Set Value
P0-D1	Submode 1	-	0	7	6	3
P0-D2	Submode 2	-	0	7	0	0
P0-D3	Modbus station of serial port 2	-	1	255	1	1
P0-D4	Parameter of serial port 2	-	0000	2209	2206	2206
P0-D5	Rotation direction selection	-	0	1	0	0
P0-D6	Stop mode when servo OFF or alarm / over range (OT) stop mode	-	0000	0302	0202	0202
P0-D7	T-REF distribution	-	0	3	0	0
P0-D8	V-REF distribution	-	0	1	0	0
P0-D9	Forced input terminal	-	0	3	0	0
P0-16	Forced ON the fan	-	0	1	0	0
P0-10	Regenerative resistor selection	-	0	1	0	0
P1-00	The gain of speed loop	Hz	1	5000	100	100
P1-01	Speed loop integral time	0.1ms	1	50000	400	400
P1-02	The gain of position loop	1/s	1	2000	100	100
P1-04	The gain of second speed loop	Hz	1	5000	250	250
P1-05	Integral time of second speed loop	0.1ms	1	50000	400	10000
P1-06	The gain of second position loop	1/s	1	2000	250	250
P1-09	The gain of position loop feedforward	1/s	0	100	0	0
P1-10	Feedforward filter time	0.01ms	0	65535	0	0
P2-00	Command pulse state	-	0	2	2	2
P2-01	Position command filter selection	-	0	1	0	0
P2-02	Electronic gear ratio (molecular)	-	1	65535	1	10
P2-03	Electronic gear ratio (denominator)	-	1	65535	1	1
P2-04	Position command filter time	time	0	128	0	0
P2-06	Command pulse frequency at rated speed	100Hz	1	10000	5000	5000

Notes: Forced input terminal
0
1: S01 terminal has signal output.
2: S02 terminal has signal output.
3: S03 terminal has signal output.

Modify anytime, effective re-power

Modify OFF, effective ON

Modify anytime, effective immediately

Read-only

Modified

Communication status: on-line

The currently selected row is colored in dark blue.

DS2 Servo Driver

File Tools Help

Communication Parameter Comparison Monitor Alarm

Servo ready (bb state)

Parameter

Open Save

Write Refresh

Overview

Overview of P Group

- P0 - Function Selection
- P1 - Control Parameters
- P2 - Position Control
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- P4 - Torque Control
- P5 - Signal Parameter Setting
- U Group Monitor State Contents
 - U0 - Monitoring Mode

Serial Number	Name	Unit	Min	Max	Default Value	Set Value
P0-D1	Submode 1	-	0	7	6	3
P0-D2	Submode 2	-	0	7	0	0
P0-D3	Modbus station of serial port 2	-	1	255	1	1
P0-D4	Parameter of serial port 2	-	0000	2209	2206	2206
P0-D5	Rotation direction selection	-	0	1	0	0
P0-D6	Stop mode when servo OFF or alarm / over range (OT) stop mode	-	0000	0302	0202	0202
P0-D7	T-REF distribution	-	0	3	0	0
P0-D8	V-REF distribution	-	0	1	0	0
P0-D9	Forced input terminal	-	0	3	0	0
P0-16	Forced ON the fan	-	0	1	0	0
P0-10	Regenerative resistor selection	-	0	1	0	0
P1-00	The gain of speed loop	Hz	1	5000	100	100
P1-01	Speed loop integral time	0.1ms	1	50000	400	400
P1-02	The gain of position loop	1/s	1	2000	100	100
P1-04	The gain of second speed loop	Hz	1	5000	250	250
P1-05	Integral time of second speed loop	0.1ms	1	50000	400	10000
P1-06	The gain of second position loop	1/s	1	2000	250	250
P1-09	The gain of position loop feedforward	1/s	0	100	0	0
P1-10	Feedforward filter time	0.01ms	0	65535	0	0
P2-00	Command pulse state	-	0	2	2	2
P2-01	Position command filter selection	-	0	1	0	0
P2-02	Electronic gear ratio (molecular)	-	1	65535	1	10
P2-03	Electronic gear ratio (denominator)	-	1	65535	1	1
P2-04	Position command filter time	time	0	128	0	0
P2-06	Command pulse frequency at rated speed	100Hz	1	10000	5000	5000

Notes: Submode 1
0 file
1: Torque (internal)
2: Torque (external)
3: Speed (internal)
4: Speed (external)
5: Position (internal)
6: Position (external)
7: Speed (pulse)

Modify anytime, effective re-power

Modify OFF, effective ON

Modify anytime, effective immediately

Read-only

Modified

Communication status: on-line

When colored in pink, the parameter can be changed anytime, but it will be applied after re-powering the servo drive.

DS2 Servo Driver

File Tools Help

Communication Parameter Comparison Monitor Alarm

Servo ready (bb state)

Parameter

Overview

Open Save

Write

Refresh

Serial Number	Name	Unit	Min	Max	Default Value	Set Value
P0-D1	Submode 1	-	0	7	6	3
P0-D2	Submode 2	-	0	7	0	0
P0-D3	Modbus station of serial port 2	-	1	255	1	1
P0-D4	Parameter of serial port 2	-	0000	2299	2206	2206
P0-D5	Rotation direction selection	-	0	1	0	0
P0-D6	Stop mode when servo OFF or alarm / over range (OT) stop mode	-	0000	0302	0202	0202
P0-D7	T-REF distribution	-	0	3	0	0
P0-D8	V-REF distribution	-	0	1	0	0
P0-D9	Forced input terminal	-	0	3	0	0
P0-D10	Forced ON the fan	-	0	1	0	0
P0-D11	Regenerative resistor selection	-	0	1	0	0
P1-D0	The gain of speed loop	Hz	1	5000	100	100
P1-D1	Speed loop integral time	0.1ms	1	50000	400	400
P1-D2	The gain of position loop	1/s	1	2000	100	100
P1-D3	The gain of second speed loop	Hz	1	5000	250	250
P1-D4	Integral time of second speed loop	0.1ms	1	50000	400	10000
P1-D5	The gain of second position loop	1/s	1	2000	250	250
P1-D6	The gain of position loop feedforward	Hz	0	100	0	0
P1-D7	Feedforward filter time	0.01ms	0	65535	0	0
P2-D0	Command pulse state	-	0	2	2	2
P2-D1	Position command filter selection	-	0	1	0	0
P2-D2	Electronic gear ratio (molecular)	-	1	65535	1	10
P2-D3	Electronic gear ratio (denominator)	-	1	65535	1	1
P2-D4	Position command filter time	time	0	128	0	0
P2-D5	Command pulse frequency at rated speed	100Hz	1	10000	5000	5000

Notes: Submode 1
 0: Idle
 1: Torque (Internal)
 2: Torque (External)
 3: Speed (Internal)
 4: Speed (External)
 5: Position (Internal)
 6: Position (External)
 7: Speed (pulse)

Modify anytime, effective re-power Modify OFF, effective ON Modify anytime, effective immediately Read-only Modified

Communication status: on-line

You cannot change the orange parameters when the servo is in run mode, only when it's in bb state.

DS2 Servo Driver

File Tools Help

Communication Parameter Comparison Monitor Alarm

Servo ready (bb state)

Parameter

Overview

Open Save

Write

Refresh

Serial Number	Name	Unit	Min	Max	Default Value	Set Value
P0-D1	Submode 1	-	0	7	6	3
P0-D2	Submode 2	-	0	7	0	0
P0-D3	Modbus station of serial port 2	-	1	255	1	1
P0-D4	Parameter of serial port 2	-	0000	2299	2206	2206
P0-D5	Rotation direction selection	-	0	1	0	0
P0-D6	Stop mode when servo OFF or alarm / over range (OT) stop mode	-	0000	0302	0202	0202
P0-D7	T-REF distribution	-	0	3	0	0
P0-D8	V-REF distribution	-	0	1	0	0
P0-D9	Forced input terminal	-	0	3	0	0
P0-D10	Forced ON the fan	-	0	1	0	0
P0-D11	Regenerative resistor selection	-	0	1	0	0
P1-D0	The gain of speed loop	Hz	1	5000	100	100
P1-D1	Speed loop integral time	0.1ms	1	50000	400	400
P1-D2	The gain of position loop	1/s	1	2000	100	100
P1-D3	The gain of second speed loop	Hz	1	5000	250	250
P1-D4	Integral time of second speed loop	0.1ms	1	50000	400	10000
P1-D5	The gain of second position loop	1/s	1	2000	250	250
P1-D6	The gain of position loop feedforward	Hz	0	100	0	0
P1-D7	Feedforward filter time	0.01ms	0	65535	0	0
P2-D0	Command pulse state	-	0	2	2	2
P2-D1	Position command filter selection	-	0	1	0	0
P2-D2	Electronic gear ratio (molecular)	-	1	65535	1	10
P2-D3	Electronic gear ratio (denominator)	-	1	65535	1	1
P2-D4	Position command filter time	time	0	128	0	0
P2-D5	Command pulse frequency at rated speed	100Hz	1	10000	5000	5000

Notes: Submode 1
 0: Idle
 1: Torque (Internal)
 2: Torque (External)
 3: Speed (Internal)
 4: Speed (External)
 5: Position (Internal)
 6: Position (External)
 7: Speed (pulse)

Modify anytime, effective re-power Modify OFF, effective ON Modify anytime, effective immediately Read-only Modified

Communication status: on-line

White parameters can be changed anytime and their change is effective immediately.

DS2 Servo Driver

File Tools Help

Communication Parameter Comparison Monitor Alarm

Servo ready (bb state)

Parameter

Overview Open Save

Overview of P Group

- P0 - Function Selection
- P1 - Control Parameters
- P2 - Position Control
- P3 - Speed Control
- P4 - Torque Control
- P5 - Signal Parameter Setting
- U Group Monitor State Contents
- U0 - Monitoring Mode

Serial Number	Name	Unit	Min	Max	Default Value	Set Value
P0-01	Submode 1	-	0	7	6	3
P0-02	Submode 2	-	0	7	0	0
P0-03	Modbus station of serial port 2	-	1	255	1	1
P0-04	Parameter of serial port 2	-	0000	2299	2206	2206
P0-05	Rotation direction selection	-	0	1	0	0
P0-06	Stop mode when servo OFF or alarm / over range (OT) stop mode	-	0000	0302	0202	0202
P0-07	T-REF distribution	-	0	3	0	0
P0-08	V-REF distribution	-	0	1	0	0
P0-09	Forced input terminal	-	0	3	0	0
P0-16	Forced ON the fan	-	0	1	0	0
P0-10	Regenerative resistor selection	-	0	1	0	0
P1-00	The gain of speed loop	Hz	1	5000	100	100
P1-01	Speed loop integral time	0.1ms	1	50000	400	400
P1-02	The gain of position loop	1/s	1	2000	100	100
P1-04	The gain of second speed loop	Hz	1	5000	250	250
P1-05	Integral time of second speed loop	0.1ms	1	50000	400	10000
P1-06	The gain of second position loop	1/s	1	2000	250	250
P1-09	The gain of position loop feedforward	1/s	0	100	0	0
P1-10	Feedforward filter time	0.01ms	0	65535	0	0
P2-00	Command pulse state	-	0	2	2	2
P2-01	Position command filter selection	-	0	1	0	0
P2-02	Electronic gear ratio (molecular)	-	1	65535	1	10
P2-03	Electronic gear ratio (denominator)	-	1	65535	1	1
P2-04	Position command filter time	time	0	128	0	0
P2-05	Command pulse frequency at rated speed	100Hz	1	10000	5000	5000

Notes: Submode 1
0: Idle
1: Torque (Internal)
2: Torque (Serial)
3: Speed (Internal)
4: Speed (Serial)
5: Position (Internal)
6: Position (Serial)
7: Speed (Serial)

Modify anytime, effective re-power Modify OFF, effective ON Modify anytime, effective immediately Read-only Modified

Communication status: on-line

Parameters colored in grey are read-only (monitor U parameters), so their value cannot be changed by user.

DS2 Servo Driver

File Tools Help

Communication Parameter Comparison Monitor Alarm

Servo ready (bb state)

Parameter

Overview Open Save

Overview of P Group

- P0 - Function Selection
- P1 - Control Parameters
- P2 - Position Control
- P3 - Speed Control
- P4 - Torque Control
- P5 - Signal Parameter Setting
- U Group Monitor State Contents
- U0 - Monitoring Mode

Serial Number	Name	Unit	Min	Max	Default Value	Set Value
P0-01	Submode 1	-	0	7	6	3
P0-02	Submode 2	-	0	7	0	0
P0-03	Modbus station of serial port 2	-	1	255	1	1
P0-04	Parameter of serial port 2	-	0000	2299	2206	2206
P0-05	Rotation direction selection	-	0	1	0	0
P0-06	Stop mode when servo OFF or alarm / over range (OT) stop mode	-	0000	0302	0202	0202
P0-07	T-REF distribution	-	0	3	0	0
P0-08	V-REF distribution	-	0	1	0	0
P0-09	Forced input terminal	-	0	3	0	0
P0-16	Forced ON the fan	-	0	1	0	0
P0-10	Regenerative resistor selection	-	0	1	0	0
P1-00	The gain of speed loop	Hz	1	5000	100	100
P1-01	Speed loop integral time	0.1ms	1	50000	400	400
P1-02	The gain of position loop	1/s	1	2000	100	100
P1-04	The gain of second speed loop	Hz	1	5000	250	250
P1-05	Integral time of second speed loop	0.1ms	1	50000	400	10000
P1-06	The gain of second position loop	1/s	1	2000	250	250
P1-09	The gain of position loop feedforward	1/s	0	100	0	0
P1-10	Feedforward filter time	0.01ms	0	65535	0	0
P2-00	Command pulse state	-	0	2	2	2
P2-01	Position command filter selection	-	0	1	0	0
P2-02	Electronic gear ratio (molecular)	-	1	65535	1	10
P2-03	Electronic gear ratio (denominator)	-	1	65535	1	1
P2-04	Position command filter time	time	0	128	0	0
P2-05	Command pulse frequency at rated speed	100Hz	1	10000	5000	5000

Notes: Submode 1
0: Idle
1: Torque (Internal)
2: Torque (Serial)
3: Speed (Internal)
4: Speed (Serial)
5: Position (Internal)
6: Position (Serial)
7: Speed (Serial)

Modify anytime, effective re-power Modify OFF, effective ON Modify anytime, effective immediately Read-only Modified

Communication status: on-line

When you enter your own value for the certain parameter, it becomes colored in light blue, which means that it is added to write buffer (more in section Write to Servo).

Search Box

DS2 Servo Driver

FileToolsHelp

CommunicationParameter ComparisonMonitorAlarm

Servo ready (bb state)

Parameter

OpenSave

Overview

Overview of P Group

- P0 - Function Selection
- P1 - Control Parameters
- P2 - Position Control
- P3 - Speed Control
- P4 - Torque Control
- P5 - Signal Parameter Setting
- U Group Monitor State Contents
 - U0 - Monitoring Mode

Write

Refresh

Serial Number	Name	Unit	Min	Max	Default Value	Set Value
P0-01	Submode 1	-	0	7	6	3
P0-02	Submode 2	-	0	7	0	0
P0-03	Modbus station of serial port 2	-	1	255	1	1
P0-04	Parameter of serial port 2	-	0000	2305	2305	2306
P0-05	Rotation direction selection	-	0	1	0	0
P0-06	Stop mode when servo OFF or alarm / over range (OT) stop mode	-	0000	0302	0202	0202
P0-07	T-REF distribution	-	0	3	0	0
P0-08	V-REF distribution	-	0	1	0	0
P0-09	Forced input terminal	-	0	3	0	0
P0-10	Forced ON the fan	-	0	1	0	0
P0-10	Regenerative resistor selection	-	0	1	0	0
P1-00	The gain of speed loop	Hz	1	5000	100	100
P1-01	Speed loop integral time	0.1ms	1	50000	400	400
P1-02	The gain of position loop	1/s	1	2000	100	100
P1-04	The gain of second speed loop	Hz	1	5000	250	250
P1-05	Integral time of second speed loop	0.1ms	1	50000	400	10000
P1-06	The gain of second position loop	1/s	1	2000	250	250
P1-08	The gain of position loop feedforward	1/s	0	100	0	0
P1-10	Feedforward filter time	0.01ms	0	65535	0	0
P2-00	Command pulse state	-	0	2	2	2
P2-01	Position command filter selection	-	0	1	0	0
P2-02	Electronic gear ratio (molecular)	-	1	65535	1	10
P2-03	Electronic gear ratio (denominator)	-	1	65535	1	1
P2-04	Position command filter time	time	0	128	0	0
P2-05	Command pulse frequency of rated speed	100Hz	1	10000	5000	5000

Notes: Submode 1
0: Idle
1: Torque (Internal)
2: Torque (Serial)
3: Speed (Internal)
4: Speed (Serial)
5: Position (Internal)
6: Position (Serial)
7: Speed (pulse)

Modify anytime, effective re-power

Modify OFF, effective ON

Modify anytime, effective immediately

Read-only

Modified

Communication status: on-line

You can search for the certain term or part of the term in table ("Name" column) by writing the search term and pressing ENTER key on your keyboard.

DS2 Servo Driver

FileToolsHelp

CommunicationParameter ComparisonMonitorAlarm

Servo ready (bb state)

Parameter

OpenSave

Overview

Overview of P Group

- P0 - Function Selection
- P1 - Control Parameters
- P2 - Position Control
- P3 - Speed Control
- P4 - Torque Control
- P5 - Signal Parameter Setting
- U Group Monitor State Contents
 - U0 - Monitoring Mode

Write

offset

Refresh

Serial Number	Name	Unit	Min	Max	Default Value	Set Value
P5-24	/CLR clear pulse offset dtt	-	0000	0016	Input term. dtt	0000
P5-25	/CHGstp step change signal dtt	-	0000	0016	Input term. dtt	0000
P5-26	/COIN positioning finished	-	0000	0013	Output term. dtt	0001
P5-29	/ACMP speed encoder checking dtt	-	0000	0013	Output term. dtt	0000
P5-30	/TCON rotation checking dtt	-	0000	0013	Output term. dtt	0000
P5-31	/S-RDY ready dtt	-	0000	0013	Output term. dtt	0003
P5-32	/CLT torque limit dtt	-	0000	0013	Output term. dtt	0000
P5-33	/VLT speed limit checking dtt	-	0000	0013	Output term. dtt	0000
P5-34	/BK brake lock dtt	-	0000	0013	Output term. dtt	0000
P5-35	/WARN warn dtt	-	0000	0013	Output term. dtt	0000
P5-36	/WDR near dtt	-	0000	0013	Output term. dtt	0000
P5-37	/ALM alarm dtt	-	0000	0013	Output term. dtt	0002
P5-38	/Z encoder Z signal dtt	-	0000	0013	Output term. dtt	0000
U-00	Actual speed of motor	rpm				0
U-01	Input speed command	rpm				0
U-02	Internal torque command	%				0
U-03	Rotate angle (mechanism angle)	1°				173.8
U-04	Rotate angle (electrical angle)	1°				335.2
U-05	Bus voltage	1V				312
U-06	Module temperature	1°C				34.5
U-07	Input command pulse speed	rpm				0
U-08	Pulse value of shift command	command pulse				0
U-10	Rotate angle (encoder value)	encoder pulse				4692
U-12	Pulse value of input command	pulse command				0
U-14	Pulse value of feedback command	pulse command				0

Notes: Submode 1
0: Idle
1: Torque (Internal)
2: Torque (Serial)
3: Speed (Internal)
4: Speed (Serial)
5: Position (Internal)
6: Position (Serial)
7: Speed (pulse)

Modify anytime, effective re-power

Modify OFF, effective ON

Modify anytime, effective immediately

Read-only

Modified

Communication status: on-line

DS2 Servo Driver

File Tools Help

Communication Parameter Comparison Monitor Alarm

Servo ready (bb state)

Parameter

Open Save

Overview

Write: mel Refresh

Serial Number	Name	Unit	Min	Max	Default Value	Set Value
P2-01	Position command filter selection	-	0	1	0	0
P2-02	Electronic gear ratio (molecular)	-	1	65535	1	10
P2-03	Electronic gear ratio (denominator)	-	1	65535	1	1
P2-04	Position command filter time	ms	0	128	0	0
P2-05	Command pulse frequency at rated speed	100Hz	1	10000	5000	5000
P2-07	Speed command pulse filter time	0.1ms	0	1000	20	20
P2-10	Internal position mode setting	-	-	-	0000	0000
P2-11	First segment pulse (low bit)	1	-9999	9999	0	0
P2-12	First segment pulse (high bit)	1	-9999	9999	0	0
P2-13	First segment speed	0.1rpm	0	50000	0	0
P2-14	First segment adjustment time	ms	0	65535	0	0
P2-15	First segment command filter time	0.1ms	0	65535	0	0
P2-94	Find the original point / the signal quantity point	-	00	1F	02	02
P2-95	The speed of closing the proximity switch	0.1rpm	0	50000	600	600
P2-96	The speed of leaving the proximity switch	0.1rpm	0	50000	100	100
P2-97	Set segment through communication	-	00	16	00	00
P3-00	Analog value of rated speed	0.01V	150	3000	1000	1000
P3-01	Internal setting speed 1	rpm	-5000	5000	100	100
P3-02	Internal setting speed 2	rpm	-5000	5000	200	200
P3-03	Internal setting speed 3	rpm	-5000	5000	300	450
P3-04	JOG speed	rpm	0	1000	100	100
P3-05	Soft start acceleration time	ms	0	65535	0	100
P3-06	Soft start deceleration time	ms	0	65535	0	100
P3-07	Speed command filter time	0.01ms	0	65535	0	20
P3-08	Speed feedback filter time	0.01ms	0	65535	20	20

Notes: Pulse deviation clear (CLR)
Pulse deviation: The difference between command pulse of controller (such as PLC) and feedback pulse of servo in position mode.
Its unit is 1 reference unit. It is related to the reference unit of the electronic gear ratio.

Modify anytime, effective re-power Modify OFF, effective ON Modify anytime, effective immediately Read-only Modified

Communication status: on-line

Write to Servo

DS2 Servo Driver

File Tools Help

Communication Parameter Comparison Monitor Alarm

Servo ready (bb state)

Parameter

Open Save

Overview

Write: Refresh

Serial Number	Name	Unit	Min	Max	Default Value	Set Value
P3-00	Analog value of rated speed	0.01V	150	3000	1000	1000
P3-01	Internal setting speed 1	rpm	-5000	5000	100	100
P3-02	Internal setting speed 2	rpm	-5000	5000	200	200
P3-03	Internal setting speed 3	rpm	-5000	5000	300	650
P3-04	JOG speed	rpm	0	1000	100	100
P3-05	Soft start acceleration time	ms	0	65535	0	100
P3-06	Soft start deceleration time	ms	0	65535	0	100
P3-07	Speed command filter time	0.01ms	0	65535	0	20
P3-08	Speed feedback filter time	0.01ms	0	65535	20	20
P3-09	Max speed limit (MAX speed)	rpm	0	5000	Different for each type	2500
P3-10	Speed command input dead area voltage	0.01V	0	100	0	0

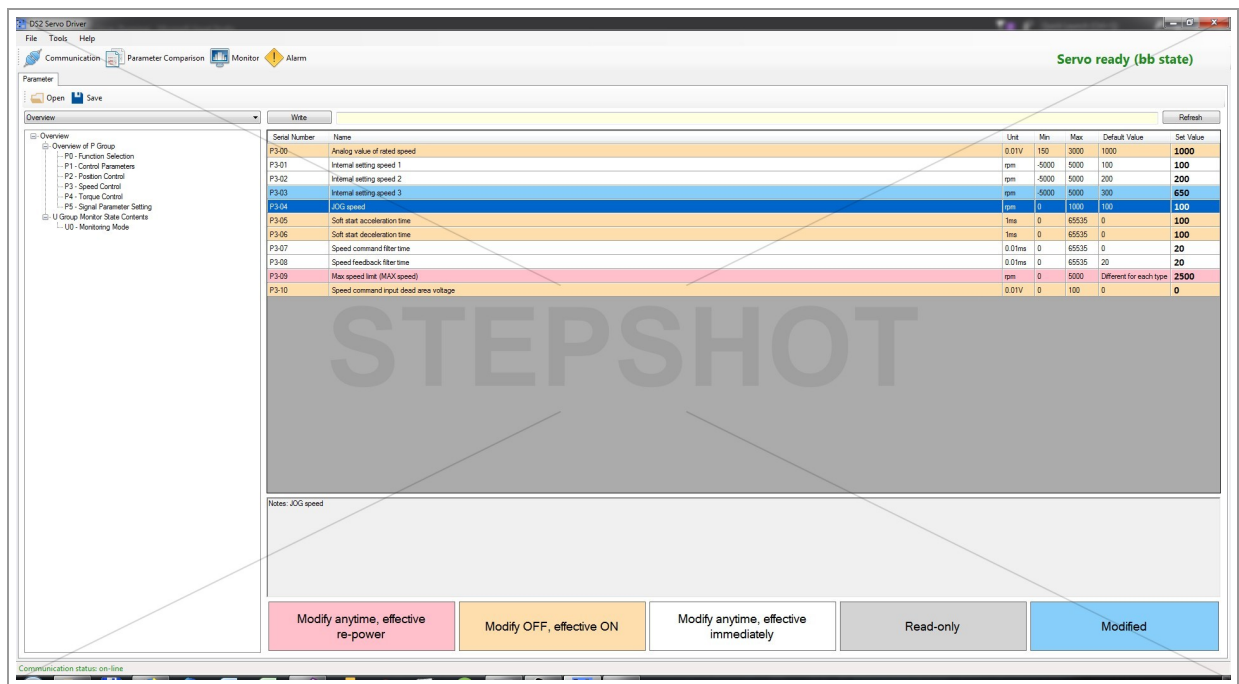
Notes: Internal setting speed 3

Modify anytime, effective re-power Modify OFF, effective ON Modify anytime, effective immediately Read-only Modified

Communication status: on-line

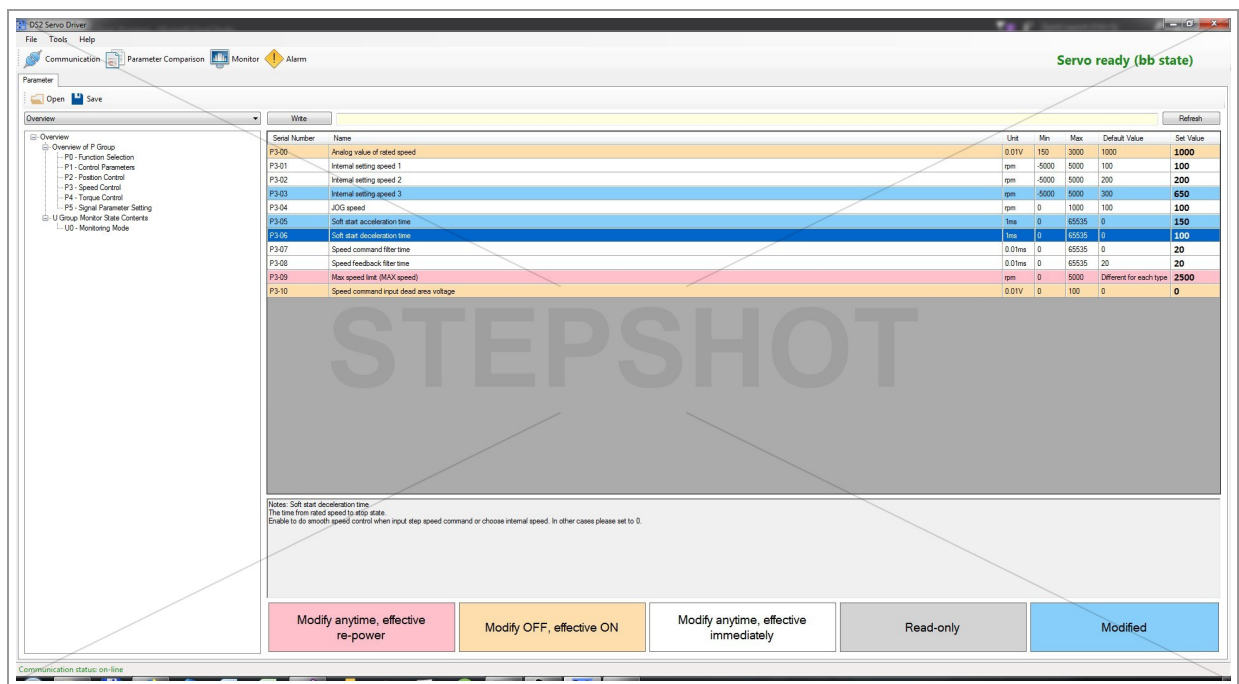
To change the current value of certain parameter double-click on it, type the value you want to write and press ENTER.

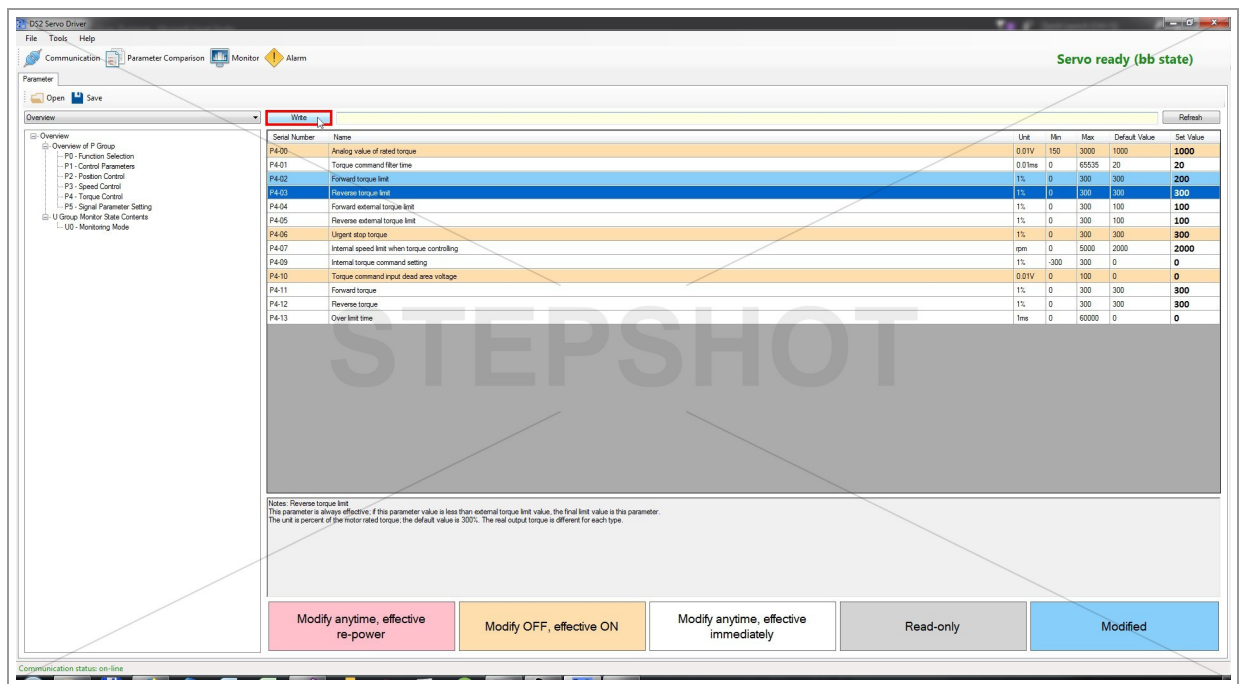
Note: Make sure that your value does not exceed the minimum and maximum limit.



By pressing ENTER, you'll notice that the row of changed parameter became colored in light blue.

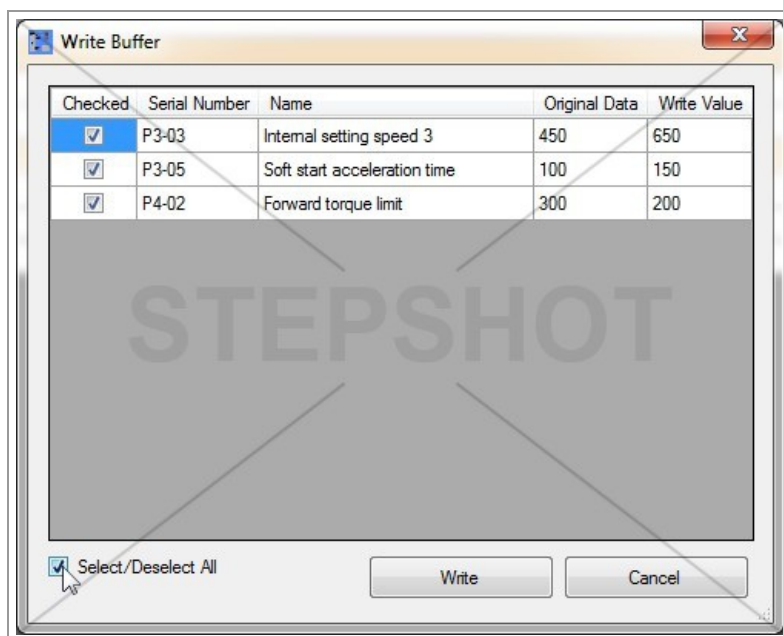
You can change the value of as many parameters as you wish before write all of them to servo (parameters doesn't have to be in the same group).





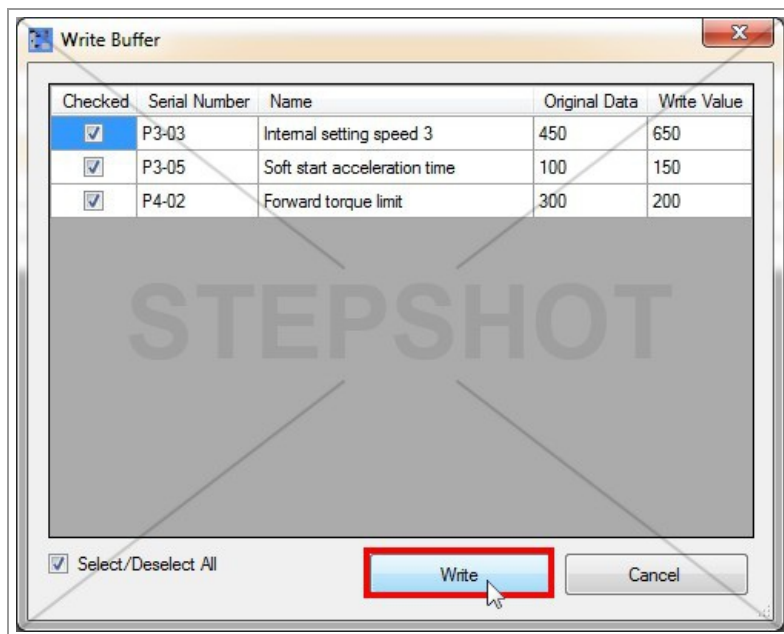
After you finish with modifying the values, click on "Write" button to select which of them you want to be written to servo driver.

Write Buffer

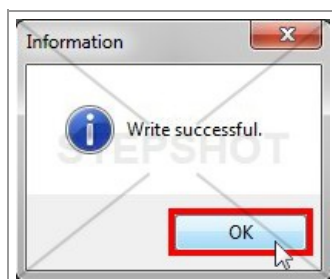


You'll get the window with mini table that contains the preview of your potential changes (write buffer).

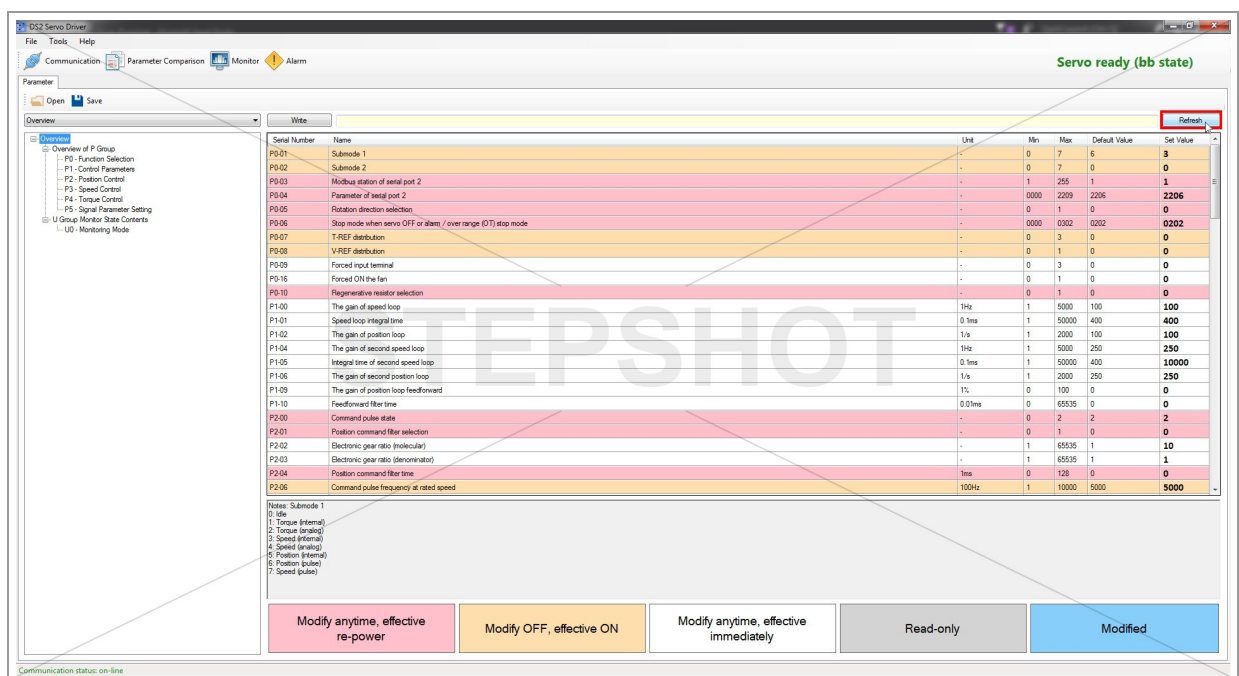
By default, all the changes are checked; if you don't want some change to be applied, you can uncheck the certain row or the whole table by clicking on "Select/Deselect All" checkbox.



Click on "Write" button in "Write Buffer" to write the new values of all selected parameters to servo.

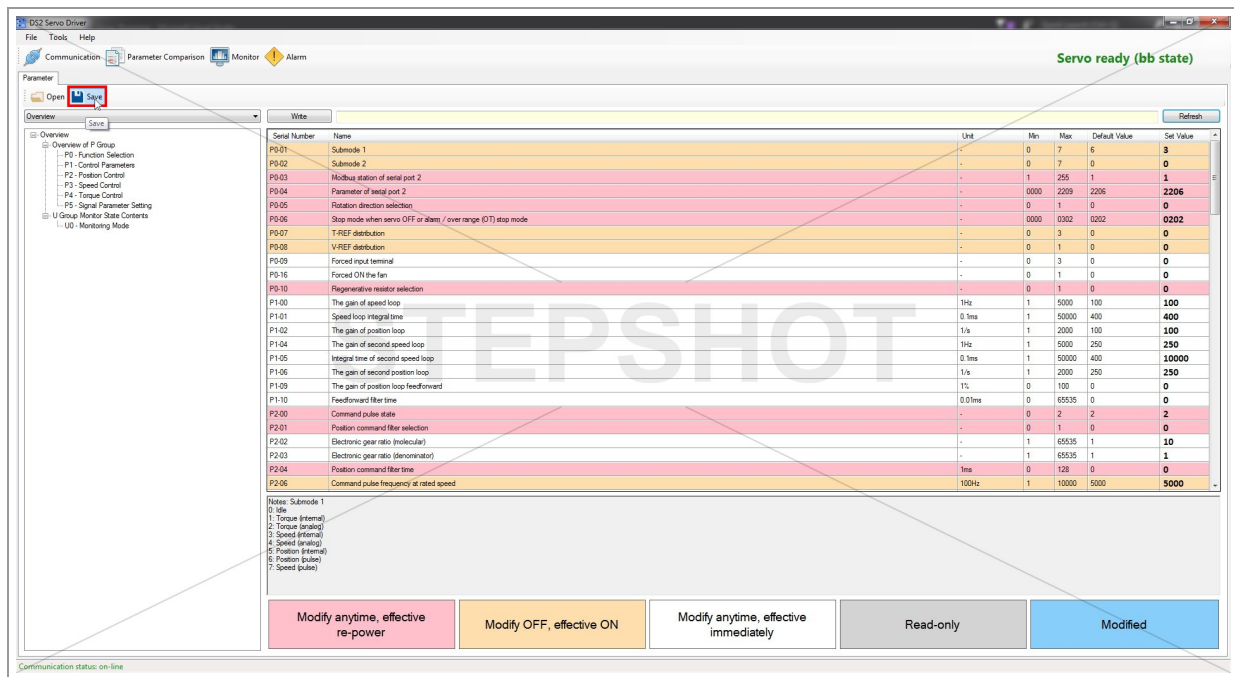


Refresh The Current Table View

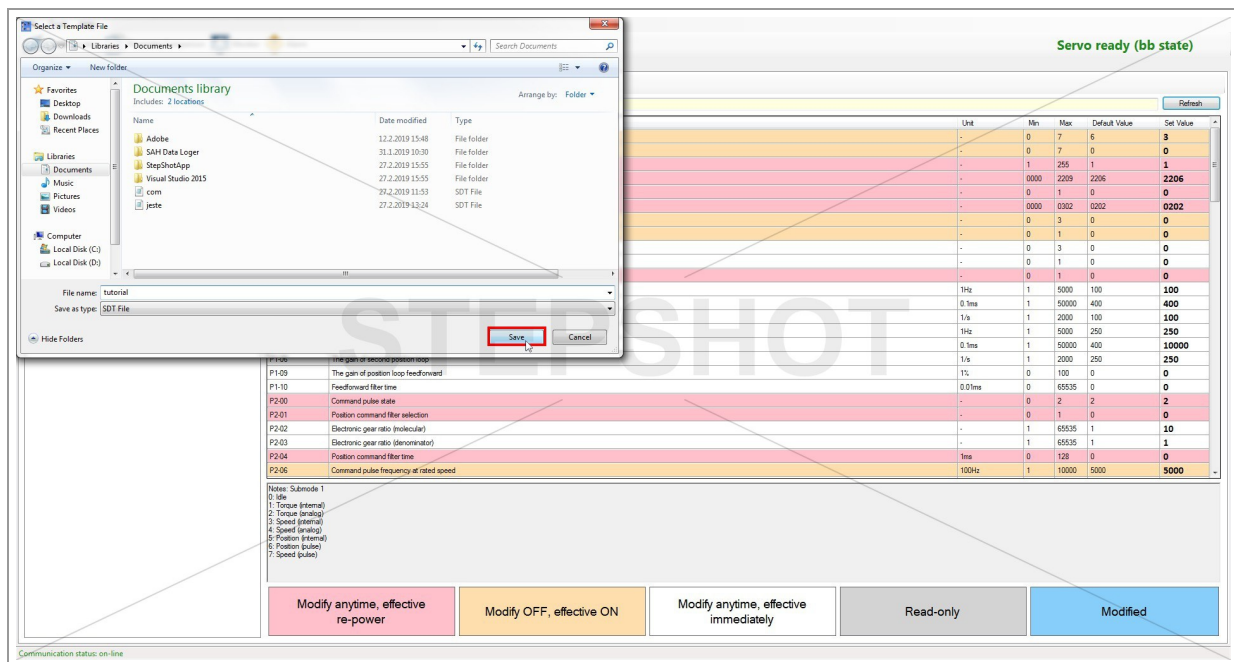


You can always reload from servo the values of parameters in the current view by clicking on "Refresh" button.

Export Data



You can export the current values of all parameters to file by clicking on "Save" button.



Enter the desired name of your template and click "Save".

Note: This file will have the unique .sdt extension that is not compatible with other similar software.

File Tools Help
Communication Parameter Comparison Monitor Alarm

Servo ready (bb state)

Parameter
Open Save

Overview

Overview of P Group
P0 - Function Selection
P1 - Control Parameters
P2 - Position Control
P3 - Speed Control
P4 - Torque Control
P5 - Signal Parameter Setting
U Group Monitor State Contents
U0 - Monitoring Mode

Serial Number	Name	Unit	Min	Max	Default Value	Set Value
P0-01	Submode 1	-	0	7	6	3
P0-02	Submode 2	-	0	7	0	0
P0-03	Modbus station of serial port 2	-	1	255	1	1
P0-04	Parameter of serial port 2	-	0000	2209	2206	2206
P0-05	Rotation direction selection	-	0	1	0	0
P0-06	Stop mode when servo OFF or alarm / over range (OT) stop mode	-	0000	0302	0302	0302
P0-07	T-REF distribution	-	0	3	0	0
P0-08	V-REF distribution	-	0	1	0	0
P0-09	Forced input terminal	-	0	3	0	0
P0-16	Forced ON the fan	-	0	1	0	0
P0-10	Regenerative resistor selection	-	0	1	0	0
P1-00	The gain of speed loop	Hz	1	5000	100	100
P1-01	Speed loop integral time	0.1ms	1	50000	400	400
P1-02	The gain of position loop	1/s	1	2000	100	100
P1-04	The gain of second speed loop	Hz	1	5000	250	250
P1-05	Integral time of second speed loop	0.1ms	1	50000	400	10000
P1-06	The gain of second position loop	1/s	1	2000	250	250
P1-09	The gain of position loop feedforward	1%	0	100	0	0
P1-10	Feedforward filter time	0.01ms	0	65535	0	0
P2-00	Command pulse state	-	0	2	2	2
P2-01	Position command filter selection	-	0	1	0	0
P2-02	Electronic gear ratio (molecular)	-	1	65535	1	10
P2-03	Electronic gear ratio (denominator)	-	1	65535	1	1
P2-04	Position command filter time	time	0	128	0	0
P2-06	Command pulse frequency at rated speed	100Hz	1	10000	5000	5000

Notes: Submode 1
0: Idle
1: Torque (Internal)
2: Torque (Analog)
3: Speed (Internal)
4: Speed (Analog)
5: Position (Internal)
6: Position (Analog)
7: Speed (pulse)

Modify anytime, effective re-power Modify OFF, effective ON Modify anytime, effective immediately Read-only Modified

Communication status: on-line

Import Data

File Tools Help
Communication Parameter Comparison Monitor Alarm

Servo ready (bb state)

Parameter
Open Save

Overview

Overview of P Group
P0 - Function Selection
P1 - Control Parameters
P2 - Position Control
P3 - Speed Control
P4 - Torque Control
P5 - Signal Parameter Setting
U Group Monitor State Contents
U0 - Monitoring Mode

Serial Number	Name	Unit	Min	Max	Default Value	Set Value
P0-01	Submode 1	-	0	7	6	3
P0-02	Submode 2	-	0	7	0	0
P0-03	Modbus station of serial port 2	-	1	255	1	1
P0-04	Parameter of serial port 2	-	0000	2209	2206	2206
P0-05	Rotation direction selection	-	0	1	0	0
P0-06	Stop mode when servo OFF or alarm / over range (OT) stop mode	-	0000	0302	0302	0302
P0-07	T-REF distribution	-	0	3	0	0
P0-08	V-REF distribution	-	0	1	0	0
P0-09	Forced input terminal	-	0	3	0	0
P0-16	Forced ON the fan	-	0	1	0	0
P0-10	Regenerative resistor selection	-	0	1	0	0
P1-00	The gain of speed loop	Hz	1	5000	100	100
P1-01	Speed loop integral time	0.1ms	1	50000	400	400
P1-02	The gain of position loop	1/s	1	2000	100	100
P1-04	The gain of second speed loop	Hz	1	5000	250	250
P1-05	Integral time of second speed loop	0.1ms	1	50000	400	10000
P1-06	The gain of second position loop	1/s	1	2000	250	250
P1-09	The gain of position loop feedforward	1%	0	100	0	0
P1-10	Feedforward filter time	0.01ms	0	65535	0	0
P2-00	Command pulse state	-	0	2	2	2
P2-01	Position command filter selection	-	0	1	0	0
P2-02	Electronic gear ratio (molecular)	-	1	65535	1	10
P2-03	Electronic gear ratio (denominator)	-	1	65535	1	1
P2-04	Position command filter time	time	0	128	0	0
P2-06	Command pulse frequency at rated speed	100Hz	1	10000	5000	5000

Notes: Submode 1
0: Idle
1: Torque (Internal)
2: Torque (Analog)
3: Speed (Internal)
4: Speed (Analog)
5: Position (Internal)
6: Position (Analog)
7: Speed (pulse)

Modify anytime, effective re-power Modify OFF, effective ON Modify anytime, effective immediately Read-only Modified

Communication status: on-line

Also you can import the previously saved template in a similar way.

Click the "Open" button and find the .sdt file you wish to load.

Communication status: on-line

Servo ready (bb state)

Select a Template File

Documents library

File name: com

SOT File

Open

Serial Number	Name	Unit	Min	Max	Default Value	Set Value
P1-01	Submode 1	-	0	7	6	3
P1-02	Submode 2	-	0	7	0	0
P1-03	Modbus station of serial port 2	-	1	255	1	1
P1-04	Parameter of serial port 2	-	0000	2209	2206	2206
P1-05	Rotation direction selection	-	0	1	0	0
P1-06	Stop mode when servo OFF or alarm / over range (OT) stop mode	-	0000	0202	0202	0202
P1-07	T-REF distribution	-	0	3	0	0
P1-08	V-REF distribution	-	0	1	0	0
P1-09	Forced input terminal	-	0	3	0	0
P1-10	Forced ON the fan	-	0	1	0	0
P1-11	Regenerative resistor selection	-	0	1	0	0
P1-12	The gain of speed loop	Hz	1	5000	100	100
P1-13	Speed loop integral time	0.1ms	1	50000	400	400
P1-14	The gain of position loop	1/s	1	2000	100	100
P1-15	The gain of second speed loop	Hz	1	5000	250	250
P1-16	The gain of second position loop	1/s	1	2000	250	250
P1-17	The gain of position loop feedforward	1%	0	100	0	0
P1-18	Feedforward filter time	0.01ms	0	65535	0	0
P1-19	Command pulse state	-	0	2	2	2
P1-20	Position command filter selection	-	0	1	0	0
P1-21	Electronic gear ratio (molecular)	-	1	65535	1	10
P1-22	Electronic gear ratio (denominator)	-	1	65535	1	1
P1-23	Position command filter time	ms	0	128	0	0
P1-24	Command pulse frequency at rated speed	100Hz	1	10000	5000	5000

Notes: Submode 1
0: Idle
1: Torque (Internal)
2: Torque (Analog)
3: Speed (Internal)
4: Speed (Analog)
5: Position (Internal)
6: Position (Pulse)
7: Speed (Pulse)

Modify anytime, effective re-power

Modify OFF, effective ON

Modify anytime, effective immediately

Read-only

Modified

File Tools Help

Communication Parameter Comparison Monitor Alarm

Servo ready (bb state)

Parameter

Open Save

Overview

Overview of P Group

P0 - Function Selection

P1 - Control Parameters

P2 - Position Control

P3 - Speed Control

P4 - Torque Control

P5 - Signal Parameter Setting

U0 - Monitoring Mode

Write

Serial Number	Name	Unit	Min	Max	Default Value	Set Value
P0-01	Submode 1	-	0	7	6	3
P0-02	Submode 2	-	0	7	0	0
P0-03	Modbus station of serial port 2	-	1	255	1	1
P0-04	Parameter of serial port 2	-	0000	2209	2206	2206
P0-05	Rotation direction selection	-	0	1	0	0
P0-06	Stop mode when servo OFF or alarm / over range (OT) stop mode	-	0000	0202	0202	0202
P0-07	T-REF distribution	-	0	3	0	0
P0-08	V-REF distribution	-	0	1	0	0
P0-09	Forced input terminal	-	0	3	0	0
P0-10	Forced ON the fan	-	0	1	0	0
P0-11	Regenerative resistor selection	-	0	1	0	0
P1-01	The gain of speed loop	Hz	1	5000	100	100
P1-02	Speed loop integral time	0.1ms	1	50000	400	400
P1-03	The gain of position loop	1/s	1	2000	100	100
P1-04	The gain of second speed loop	Hz	1	5000	250	250
P1-05	Integral time of second speed loop	0.1ms	1	50000	400	100000
P1-06	The gain of second position loop	1/s	1	2000	250	250
P1-07	The gain of position loop feedforward	1%	0	100	0	0
P1-08	Feedforward filter time	0.01ms	0	65535	0	0
P1-09	Command pulse state	-	0	2	2	2
P1-10	Position command filter selection	-	0	1	0	0
P1-11	Electronic gear ratio (molecular)	-	1	65535	1	10
P1-12	Electronic gear ratio (denominator)	-	1	65535	1	1
P1-13	Position command filter time	ms	0	128	0	0
P1-14	Command pulse frequency at rated speed	100Hz	1	10000	5000	5000

Notes: Submode 1
0: Idle
1: Torque (Internal)
2: Torque (Analog)
3: Speed (Internal)
4: Speed (Analog)
5: Position (Internal)
6: Position (Pulse)
7: Speed (Pulse)

Information

Template file has been successfully loaded.

OK

Modify anytime, effective re-power

Modify OFF, effective ON

Modify anytime, effective immediately

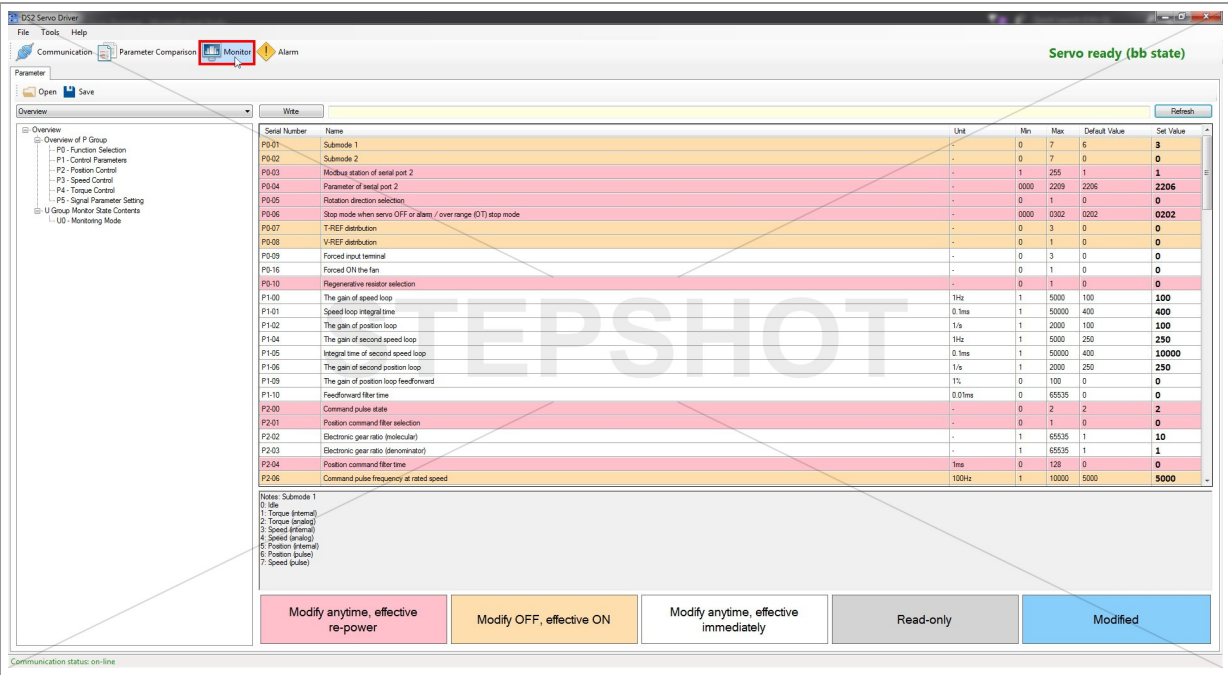
Read-only

Modified

Communication status: on-line

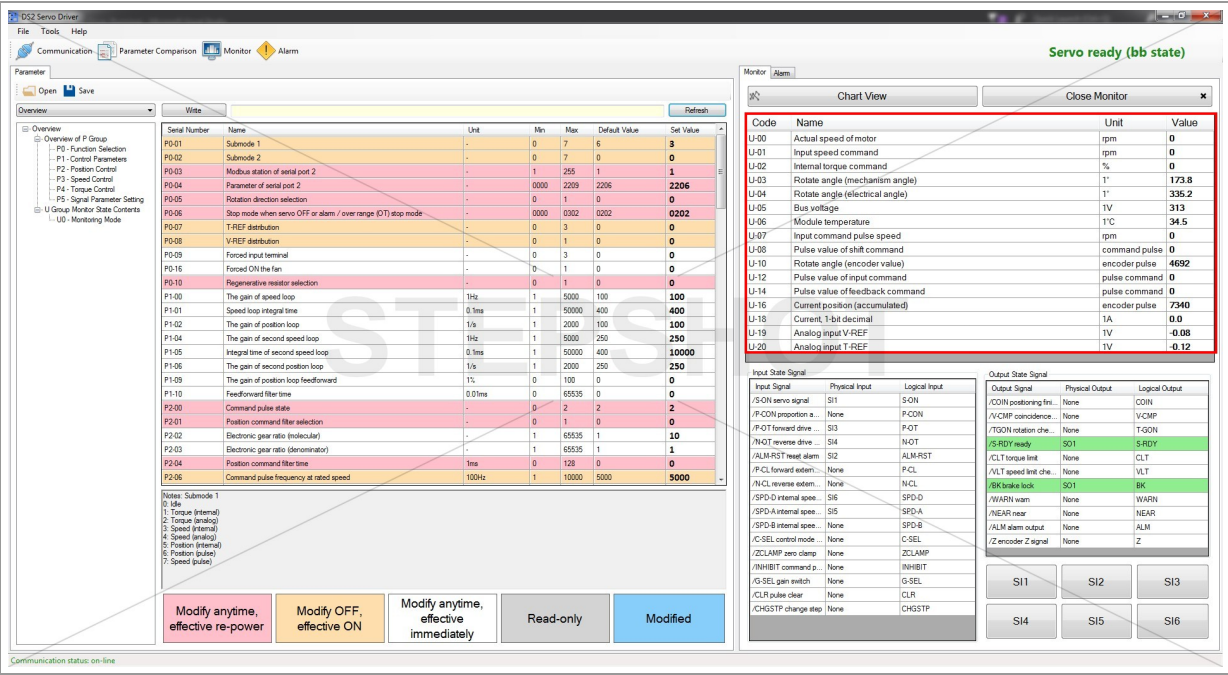
Monitor Mode

Monitor



By clicking on "Monitor" icon, the new tab with monitor parameters and input/output signal state opens on the right side.

Monitor Status Parameters



U parameters are being loaded every 500ms.

Input State Signal

The screenshot displays the D52 Servo Driver software interface. The main window is divided into several sections:

- Parameter Table:** A table listing various servo parameters (P0-01 to P2-06) with columns for Serial Number, Name, Unit, Min, Max, Default Value, and Set Value. Parameters P5-10 are highlighted in pink, indicating they are related to input signals.
- Monitor Alarm:** A section on the right showing the current state of the servo, including "Servo ready (bb state)".
- Input State Signal Table:** A table showing the status of various input signals. The table has columns for Input Signal, Physical Input, Logical Input, and Value. The "S-ON servo signal" (SI1) is highlighted in light green, indicating it is active.
- Output State Signal Table:** A table showing the status of various output signals. The "S-RDY ready" (S01) is highlighted in light green, indicating the servo is in a ready state.

Input signals are related to values of the parameters P5-10 ~ P5-25.

When you set the index of P5 input to certain value 1-6, the change of that parameter appears in input state signal table as "Physical Input".

For example: "SI1" is related to S-ON, "SI2" is related to ALM-RST, etc.

Output State Signal

The screenshot displays the D52 Servo Driver software interface, focusing on the Output State Signal table. The table lists various output signals (U-00 to U-20) with columns for Code, Name, Unit, and Value. The "S-RDY ready" (S01) is highlighted in light green, indicating the servo is in a ready state. The "S-ON servo signal" (SI1) is also highlighted in light green, indicating it is active.

Parameters in output state signal are read-only and they indicate the current output state of servo.

Parameters that are currently active on some of the physical outputs are colored in light green.

For example: S-RDY active means that servo is in ready state (bb state).

Input Commands

Signal Input Buttons

The screenshot shows the D52 Servo Driver software interface. The 'Monitor' tab is active, displaying the 'Servo ready (bb state)' indicator. The 'Input State Signal' table shows the following data:

Input Signal	Physical Input	Logical Input
/S-ON servo signal	SI1	S-ON
/P-CON proportion a...	None	P-CON
/F-OT forward drive ...	SI3	P-OT
/NOT reverse drive ...	SI4	NOT
/ALMRST wear alarm	SI2	ALMRST
/P-CL forward exten...	None	P-CL
/N-CL reverse exten...	None	N-CL
/SPD-0 internal spee...	SI6	SPD-D
/SPD-A internal spee...	SI5	SPD-A
/SPD-B internal spee...	None	SPD-B
/C-SEL control mode ...	None	C-SEL
/Z-CLAMP zero clamp	None	Z-CLAMP
/INHBIT command.s...	None	INHBIT
/G-SEL gear switch	None	G-SEL
/CLR pulse clear	None	CLR
/CHGSTP change step	None	CHGSTP

The 'Output State Signal' table shows the following data:

Output Signal	Physical Output	Logical Output
/COIN positioning fini...	None	COIN
/V-CMP coincidence...	None	V-CMP
/T-GON rotation che...	None	T-GON
/S-RDY ready	SI1	S-RDY
/CLT torque limit	None	CLT
/ALT speed limit che...	None	ALT
/BK brake lock	SI1	BK
/WARN warn	None	WARN
/NEAR near	None	NEAR
/ALM alarm output	None	ALM
/Z encoder Z signal	None	Z

The 'SI1' button is highlighted in red, and a tooltip indicates it is related to S-ON.

When you mouse hover some of the "SI" buttons, the tooltip will appear.

It indicates what logical input in input state signal table is that button related to.

In this example, SI1 is related to S-ON -> by clicking on button "SI1", S-ON input will activate (servo will switch to run mode).

Run Mode

The screenshot shows the D52 Servo Driver software interface. The 'Monitor' tab is active, displaying the 'Run mode' indicator. The 'SI1' button is highlighted in green, indicating it is the active input.

Also you'll notice that the servo state indicator is changed to "Run mode" and the pressed "SI1" button is colored to green.

Also, activated input is colored to light green.

Start Motor

The screenshot shows the 'D52 Servo Driver' software interface. The 'Monitor' tab is active, displaying a table of input and output signals. The 'SI5' button is highlighted in green, indicating it is active. The 'SPD-A' parameter is set to 'SPD-A'.

Code	Name	Unit	Value
U-00	Actual speed of motor	rpm	500
U-01	Input speed command	rpm	500
U-02	Internal torque command	%	7
U-03	Rotate angle (mechanism angle)	1°	324.4
U-04	Rotate angle (electrical angle)	1°	217.7
U-05	Bus voltage	1V	312
U-06	Module temperature	1°C	34.5
U-07	Input command pulse speed	rpm	0
U-08	Pulse value of shift command	command pulse	0
U-10	Rotate angle (encoder value)	encoder pulse	8876
U-12	Pulse value of input command	pulse command	0
U-14	Pulse value of feedback command	pulse command	0
U-16	Current position (accumulated)	encoder pulse	751513
U-18	Current, 1-bit decimal	1A	0.2
U-19	Analog input V-REF	1V	-0.10
U-20	Analog input T-REF	1V	-0.11

By clicking on "SI5" button, SPD-A activates (motor starts to rotate at a given speed).

Change Rotate Direction

The screenshot shows the 'D52 Servo Driver' software interface. The 'Monitor' tab is active, displaying a table of input and output signals. The 'SI5' button is highlighted in green, indicating it is active. The 'SPD-D' parameter is set to 'SPD-D'.

Code	Name	Unit	Value
U-00	Actual speed of motor	rpm	-499
U-01	Input speed command	rpm	-499
U-02	Internal torque command	%	-8
U-03	Rotate angle (mechanism angle)	1°	225.9
U-04	Rotate angle (electrical angle)	1°	183.7
U-05	Bus voltage	1V	313
U-06	Module temperature	1°C	34.5
U-07	Input command pulse speed	rpm	0
U-08	Pulse value of shift command	command pulse	0
U-10	Rotate angle (encoder value)	encoder pulse	6140
U-12	Pulse value of input command	pulse command	0
U-14	Pulse value of feedback command	pulse command	0
U-16	Current position (accumulated)	encoder pulse	-1011196
U-18	Current, 1-bit decimal	1A	0.2
U-19	Analog input V-REF	1V	-0.11
U-20	Analog input T-REF	1V	-0.09

SPD-D changes the current rotate direction.

Chart View

The screenshot shows the 'D52 Servo Driver' software interface. The 'Monitor' tab is active, and the 'Chart View' button is highlighted with a red box. The interface includes a 'Parameter' list on the left, a 'Monitor' table on the right, and a 'Close Monitor' button. The 'Monitor' table lists various parameters such as 'Actual speed of motor', 'Input speed command', 'Internal torque command', 'Rotate angle (mechanism angle)', 'Rotate angle (electrical angle)', 'Bus voltage', 'Module temperature', 'Pulse value of shift command', 'Rotate angle (encoder value)', 'Pulse value of input command', 'Pulse value of feedback command', 'Current position (accumulated)', 'Current, 1-bit decimal', 'Analog input V-REF', and 'Analog input T-REF'.

Click on "Chart View" button to open a new tab on the left side of your window.

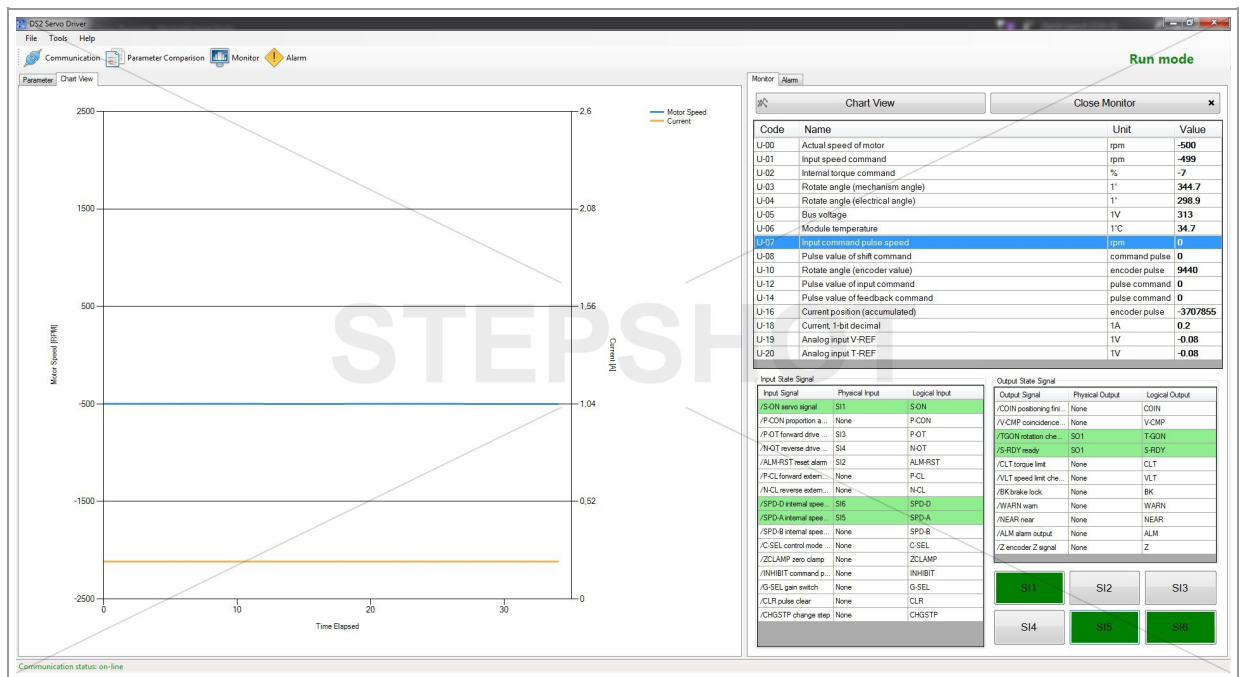
The line chart with real-time values for the actual speed of motor and the present current will appear.

Stop Motor

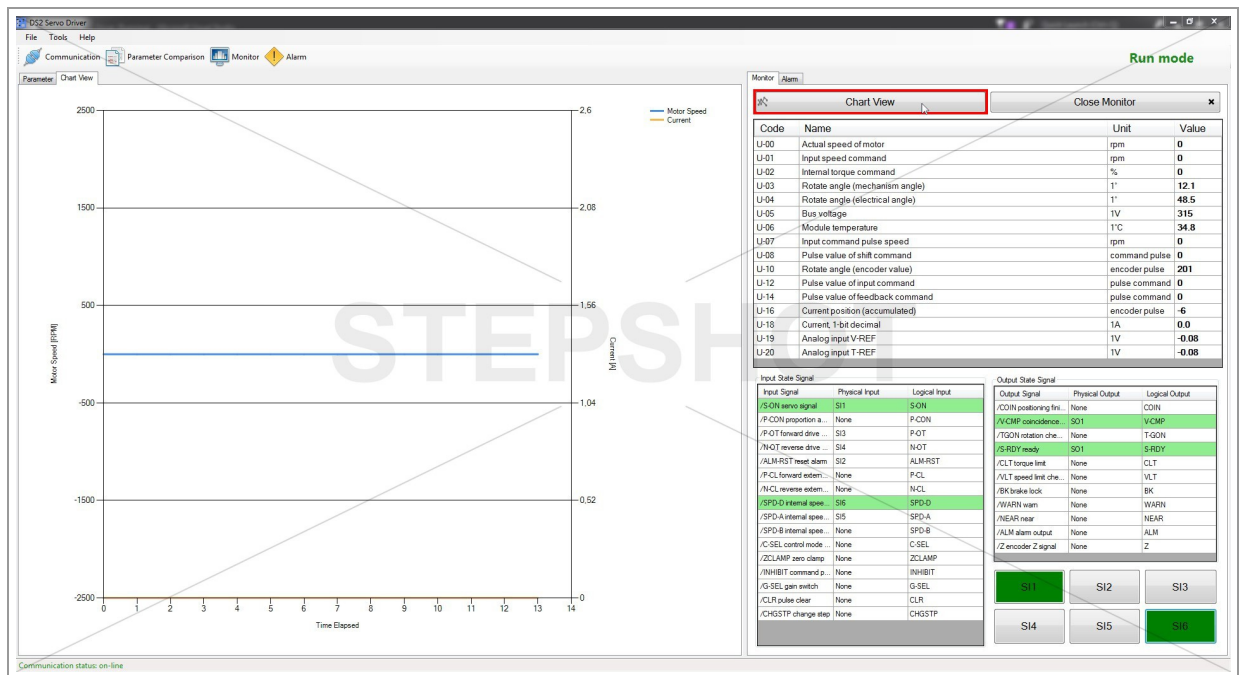
The screenshot shows the 'D52 Servo Driver' software interface with the 'Chart View' tab active. The chart displays 'Motor Speed [rpm]' (blue line) and 'Current [A]' (orange line) over 'Time Elapsed' (0 to 40 seconds). The motor speed starts at 0, rises to approximately 1500 rpm, and then falls back to 0. The current starts at 0, rises to approximately 1.5A, and then falls back to 0. The 'Monitor' table on the right shows the 'Actual speed of motor' (U-00) at 1500 rpm and the 'Current, 1-bit decimal' (U-18) at 0.00.

Stop the motor rotation by deactivating input "SI5".

You'll notice the fall of motor speed and current to 0 on the graph.

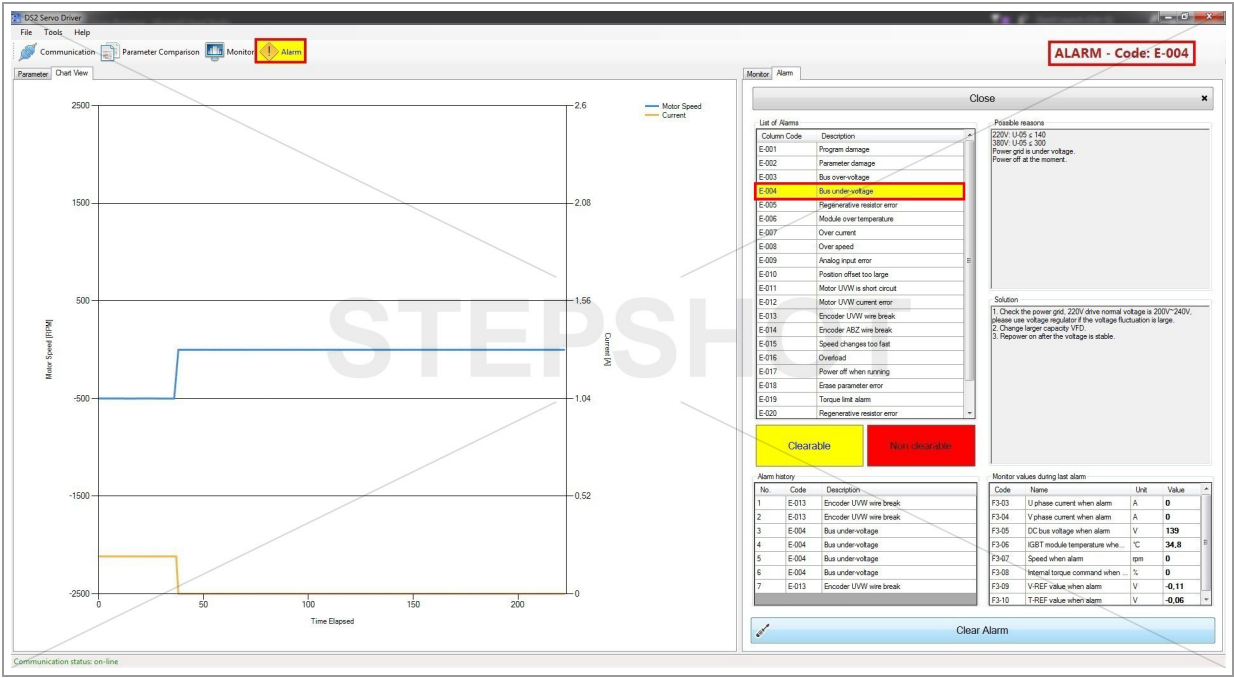


Refresh Chart View



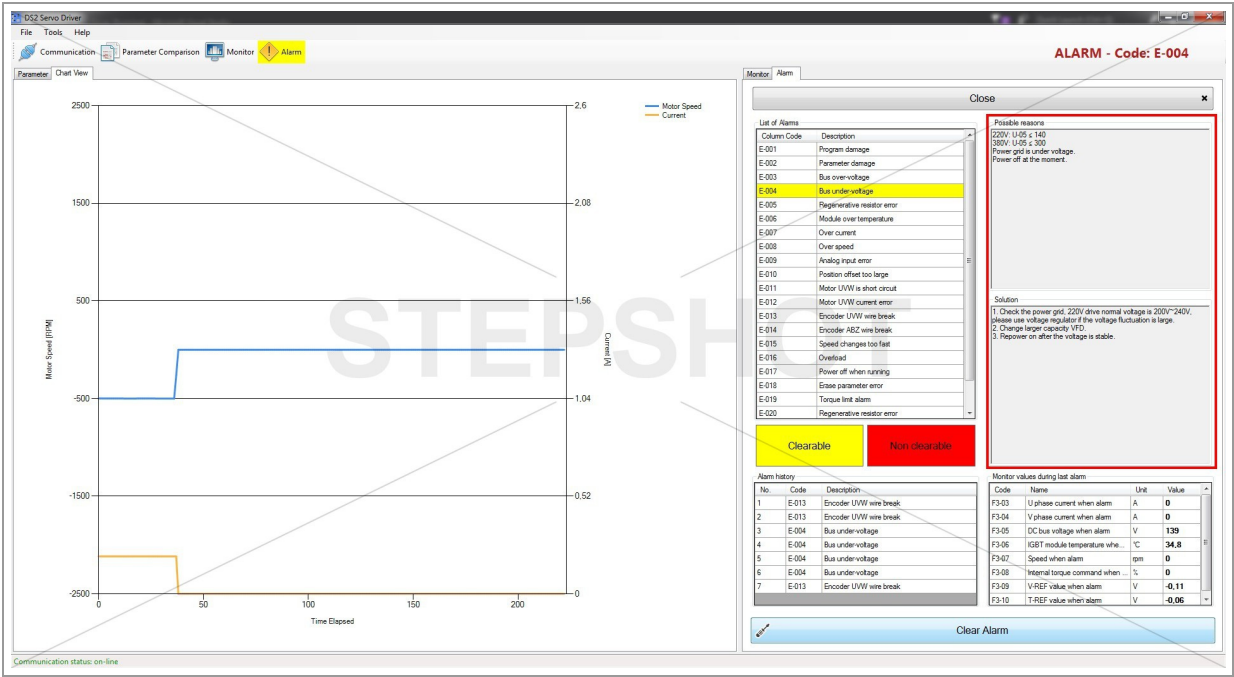
Alarm

Alarm Occur



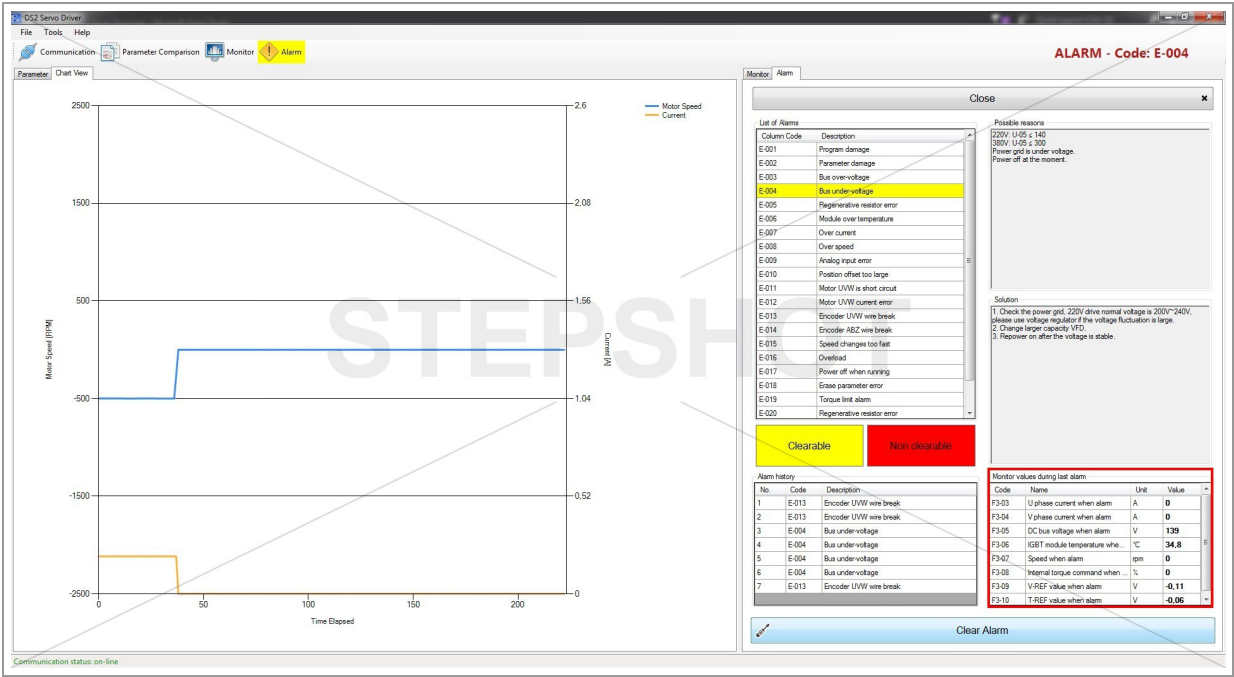
When the clearable alarm occurs, the alarm icon and the alarm code from the list of alarms get colored in yellow.

Possible Reasons and Solution



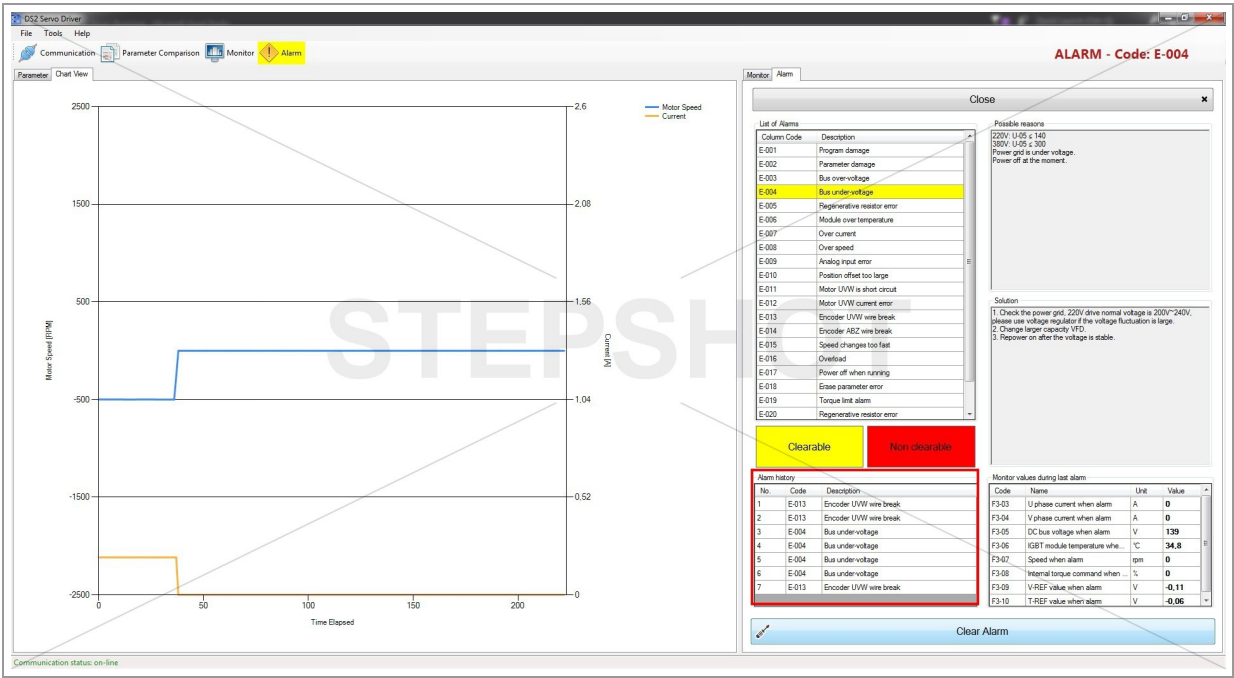
The list of possible reasons for the present error occurring and solutions for it are shown in marked textboxes.

Monitor Values During the Last Alarm



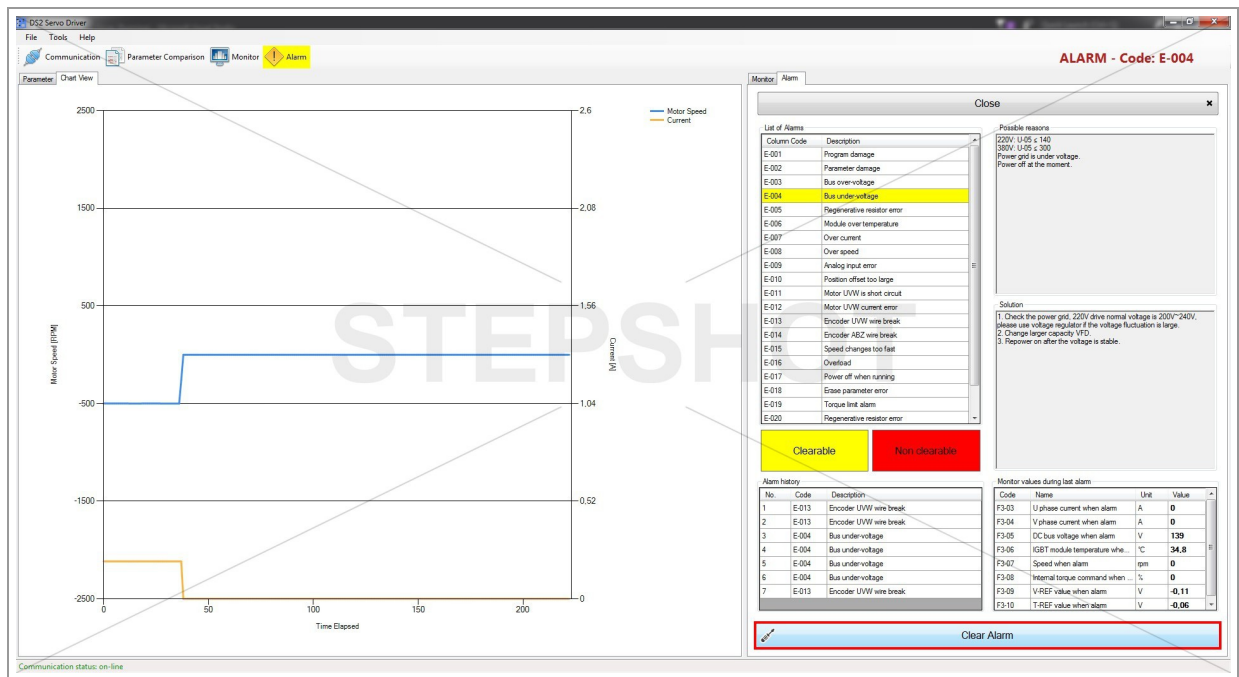
The values of some key parameters are being recorded in the moment of last occur of alarm.

Alarm History



The history of the last 7 occurred alarms can be found in the marked table.

Clear Alarm

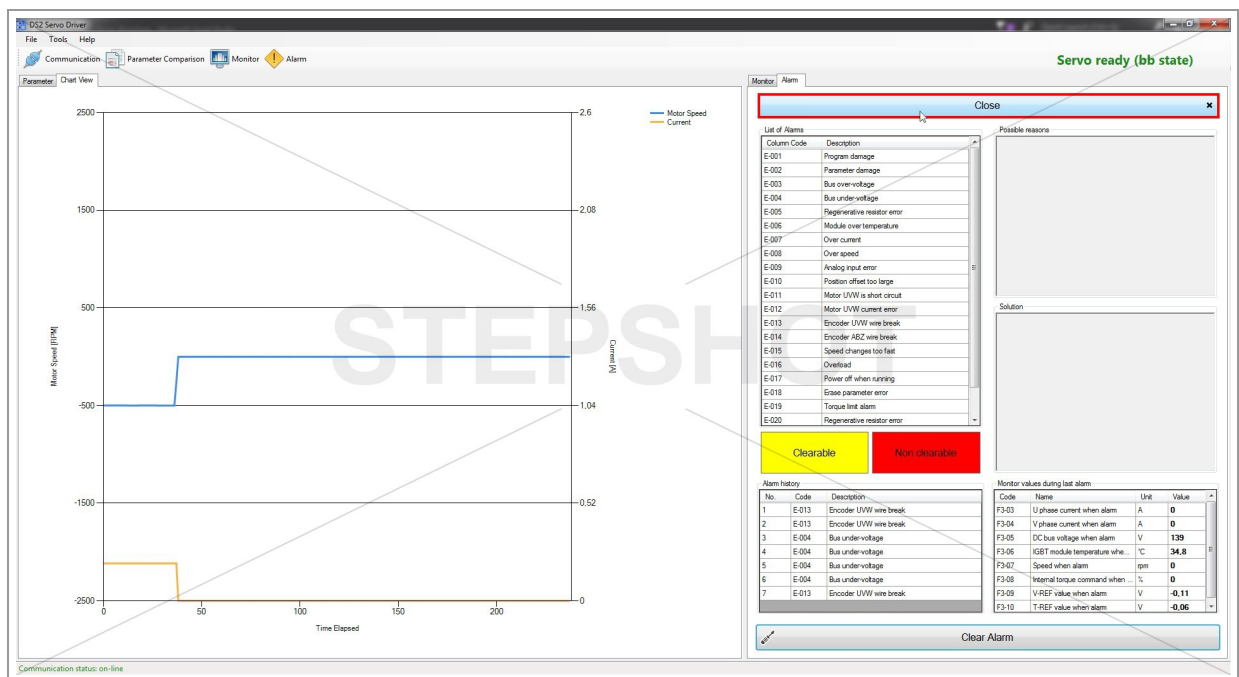


If the alarm is clearable, you can clear it and back servo to bb state by clicking the "Clear Alarm" button.

Otherwise, if the alarm color is red, you have to re-power the servo in order to clear the error.

In that case, "Clear Alarm" command cannot be applied.

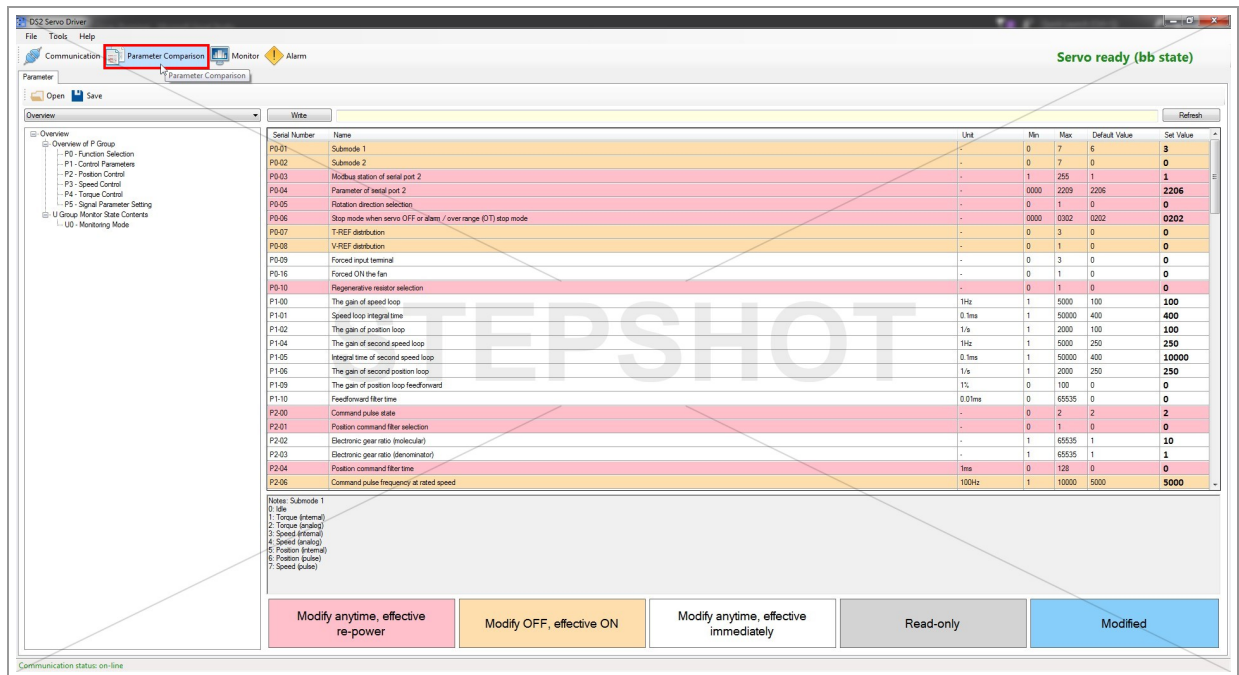
Close Monitor Mode



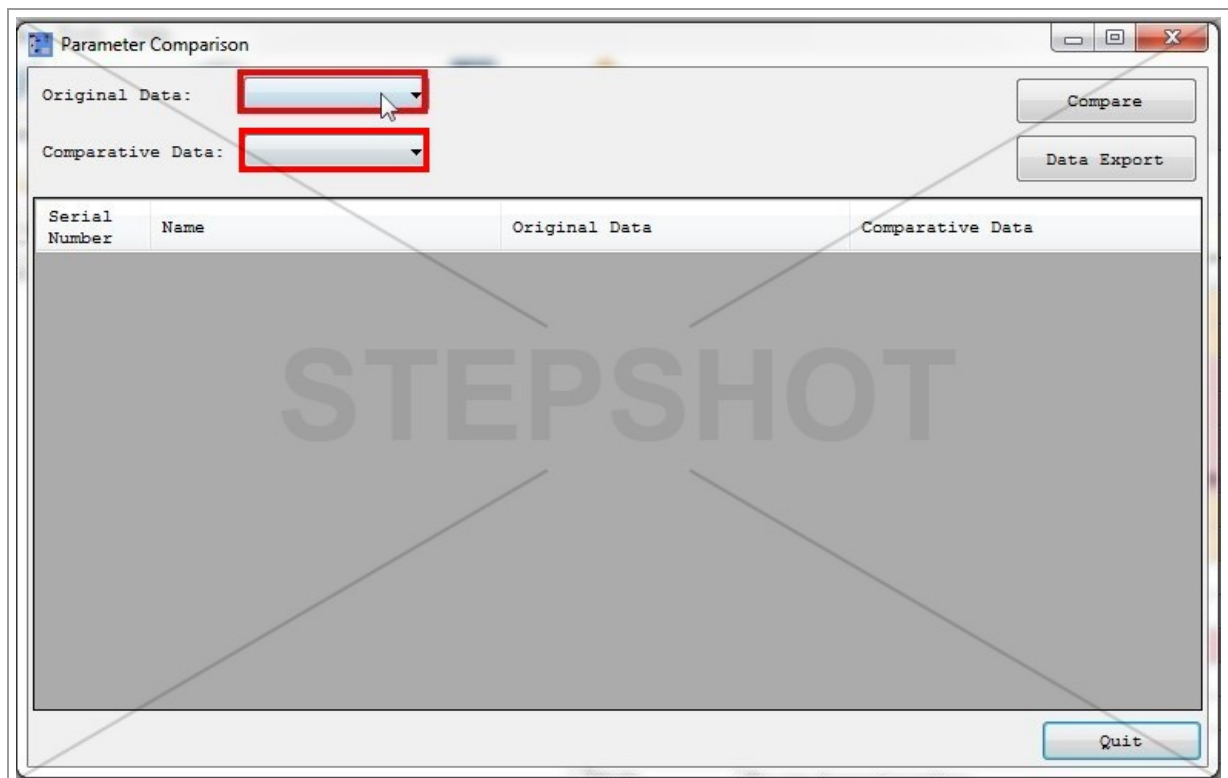
To close the monitor mode and get back to full parameter table view, click "Close" button in "Alarm" tab or "Close Monitor" button in "Monitor" tab.

Other Features

Parameter Comparison

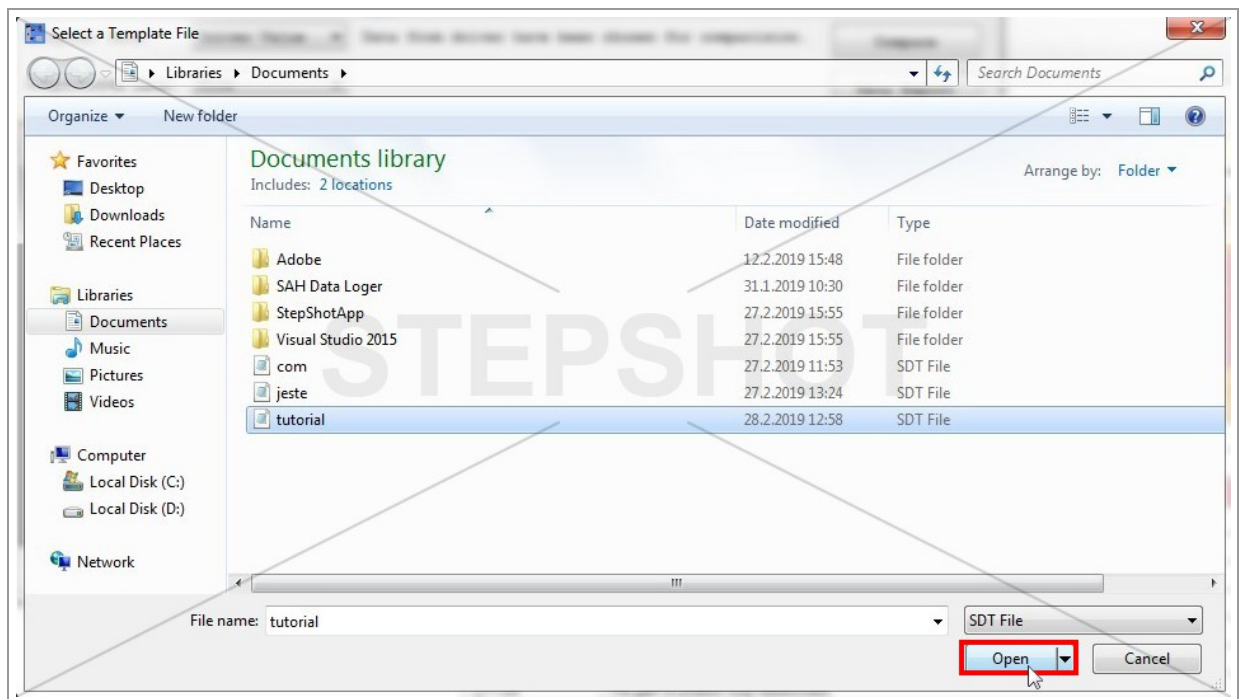
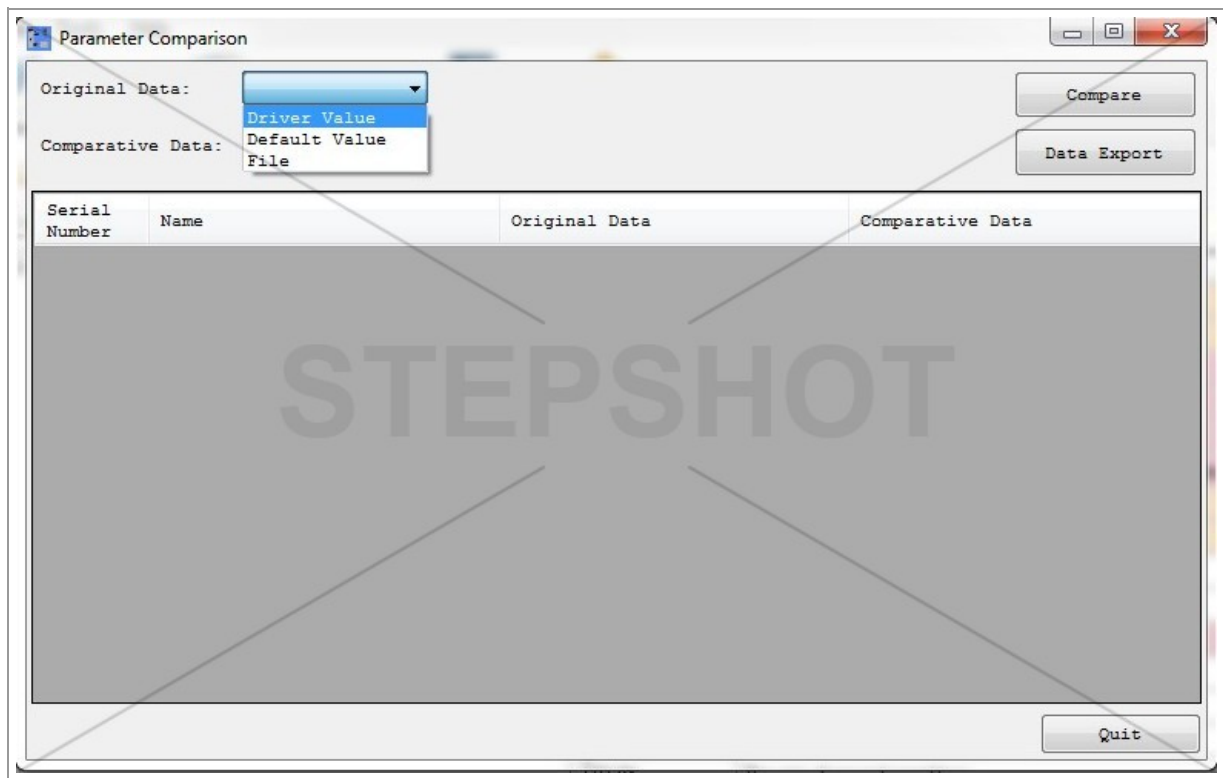


If you need to compare the data from the driver, parameter default values or data from saved file one with each other, click on "Parameter Comparison" icon.



Select the original and comparative data from dropdown menus to compare the values of all parameters.

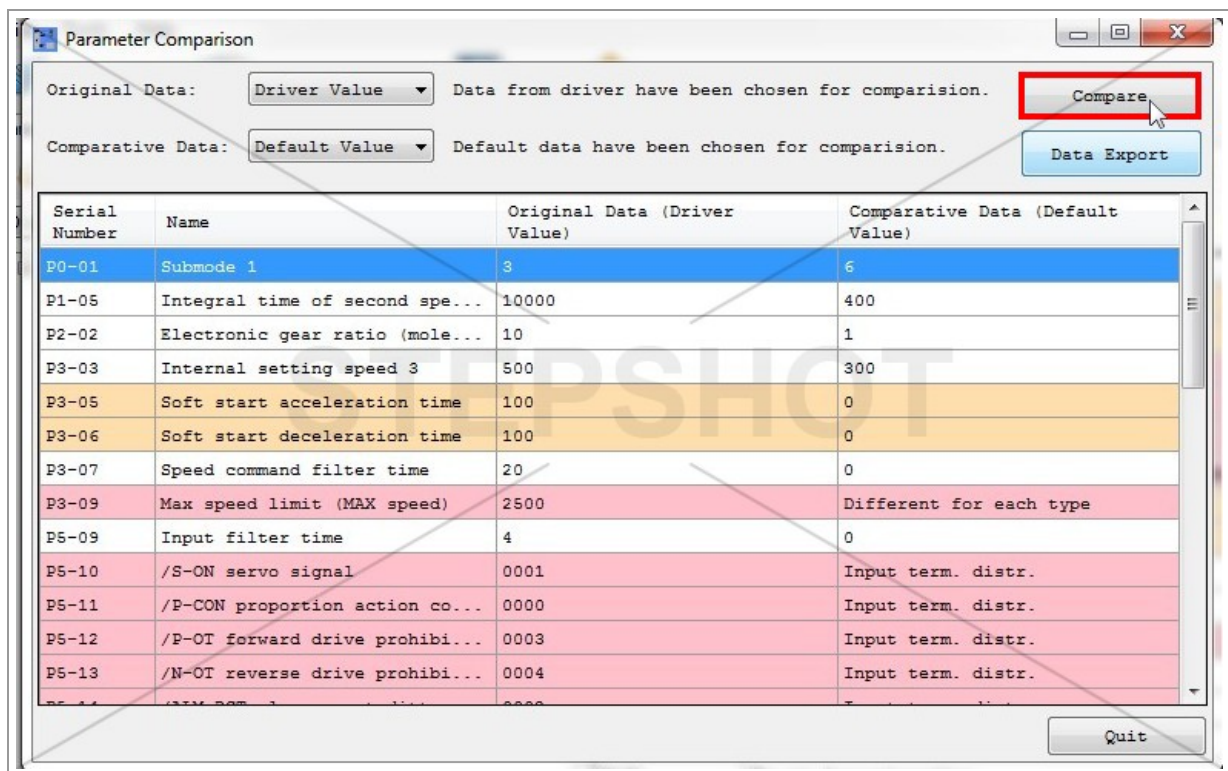
Note: Make sure that selected original and comparative data are different; otherwise, there will be nothing to compare.



If you choose "File", the open dialog box will appear and you'll be prompted to choose the exported .sdf template file.

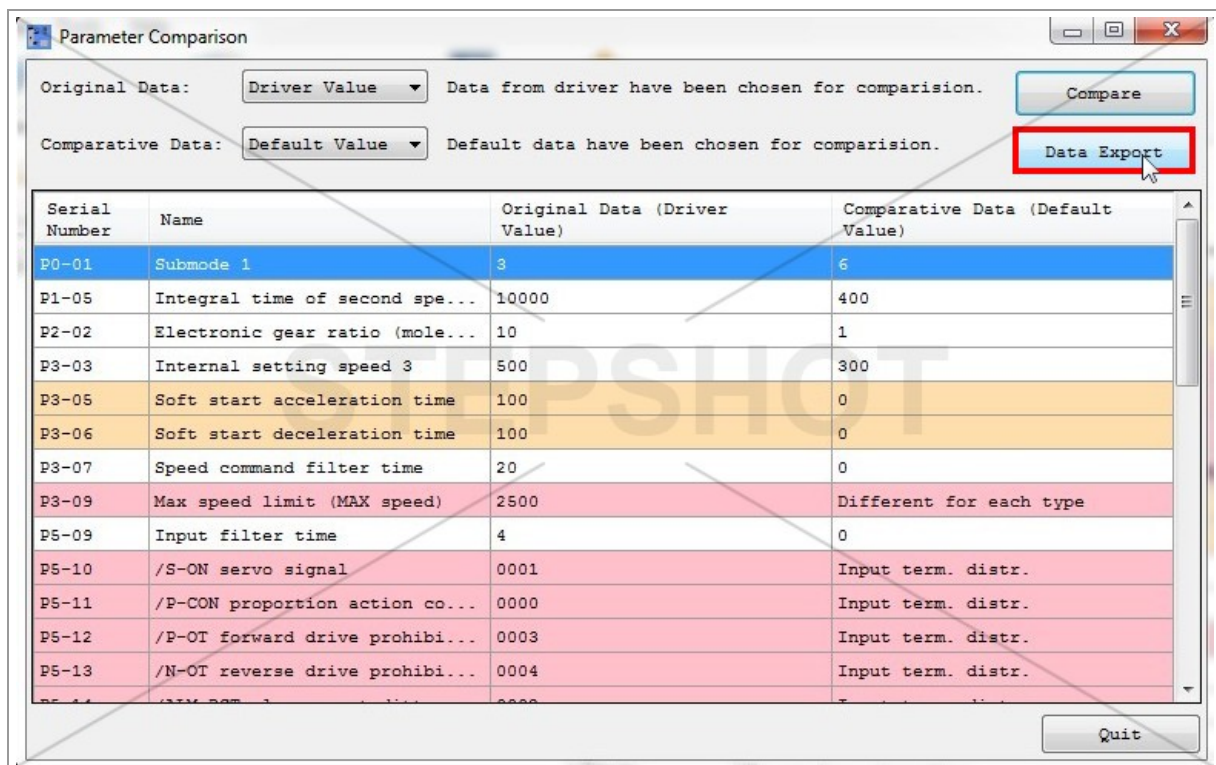
Press "Open" button to load it.

Compare The Data



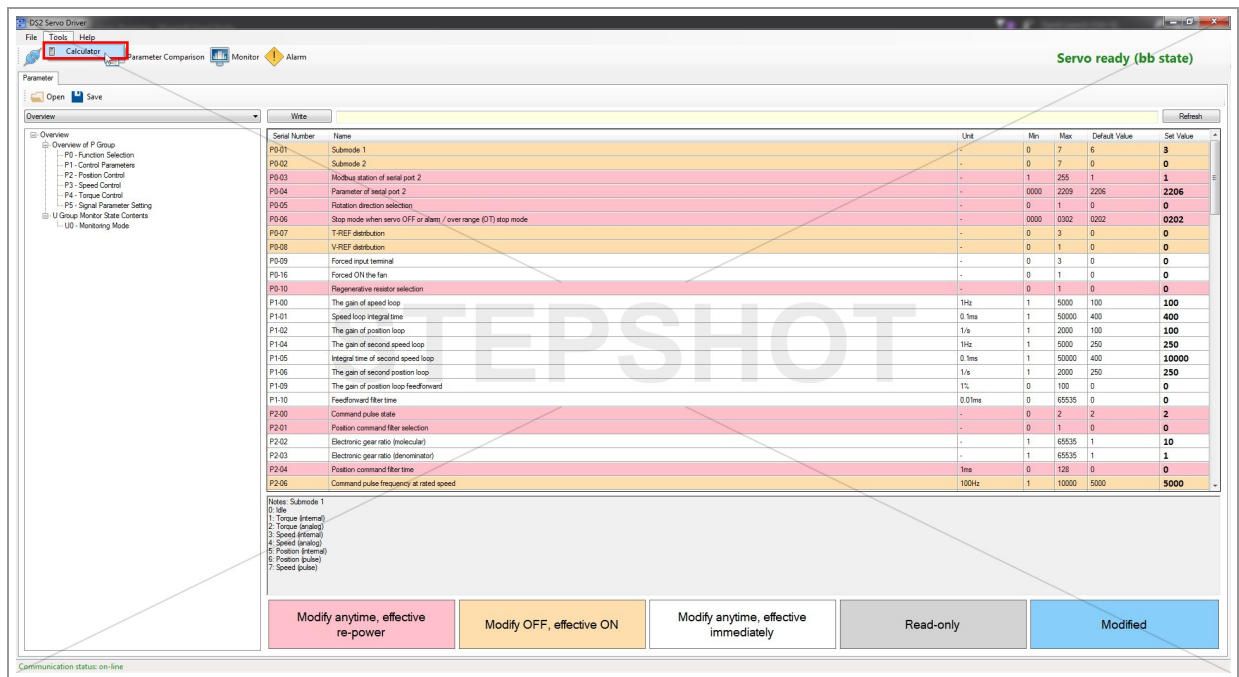
Click on "Compare" button to see the list of all parameters from selected original data which values are different than selected comparative data.

Export the Compared Data

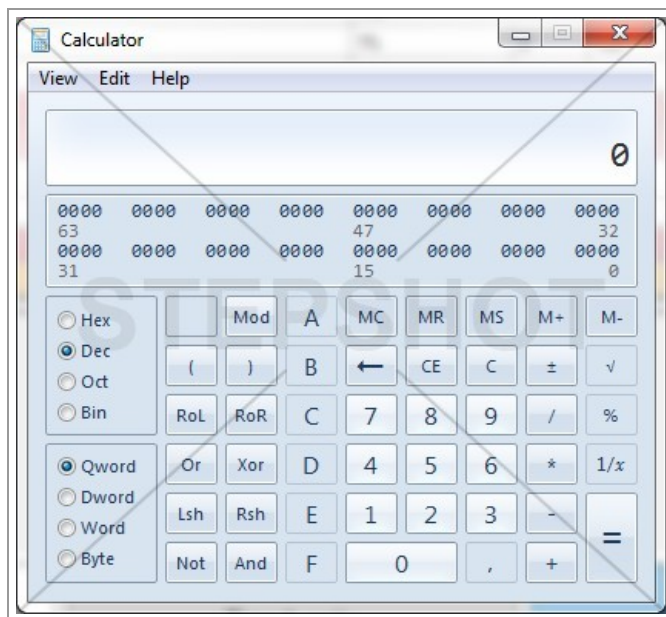


You can export the data from the table to .csv file, if you need to, by clicking "Data Export" button.

Tools



Go to Tools -> Calculator from main menu to open the classic Windows calculator.



Help

DS2 Servo Driver

File Tools Help

Comm Device Manual Software Manual About

Parameter Open Save

Overview

Overview of P Group

- P0 - Function Selection
- P1 - Control Parameters
- P2 - Position Control
- P3 - Speed Control
- P4 - Torque Control
- P5 - Signal Parameter Setting
- U Group Monitor State Contents
- U0 - Monitoring Mode

Write

Serial Number	Name	Unit	Min	Max	Default Value	Set Value
P0-01	Submode 1	-	0	7	6	3
P0-02	Submode 2	-	0	7	0	0
P0-03	Modbus station of serial port 2	-	1	255	1	1
P0-04	Parameter of serial port 2	-	0000	2209	2206	2206
P0-05	Rotation direction selection	-	0	1	0	0
P0-06	Stop mode when servo OFF or alarm / over range (OT) stop mode	-	0000	0302	0202	0202
P0-07	T-REF distribution	-	0	3	0	0
P0-08	V-REF distribution	-	0	1	0	0
P0-09	Forced input terminal	-	0	3	0	0
P0-10	Forced ON the fan	-	0	1	0	0
P0-10	Regenerative resistor selection	-	0	1	0	0
P1-00	The gain of speed loop	Hz	1	5000	100	100
P1-01	Speed loop integral time	0.1ms	1	50000	400	400
P1-02	The gain of position loop	1/s	1	2000	100	100
P1-04	The gain of second speed loop	Hz	1	5000	250	250
P1-05	Integral time of second speed loop	0.1ms	1	50000	400	10000
P1-06	The gain of second position loop	1/s	1	2000	250	250
P1-09	The gain of position loop feedforward	1/s	0	100	0	0
P1-10	Feedforward filter time	0.01ms	0	65535	0	0
P2-00	Command pulse state	-	0	2	2	2
P2-01	Position command filter selection	-	0	1	0	0
P2-02	Electronic gear ratio (molecular)	-	1	65535	1	10
P2-03	Electronic gear ratio (denominator)	-	1	65535	1	1
P2-04	Position command filter time	ms	0	128	0	0
P2-05	Command pulse frequency at rated speed	100Hz	1	10000	5000	5000

Notes: Submode 1
0. Idle
1. Torque (Internal)
2. Torque (External)
3. Speed (Internal)
4. Speed (External)
5. Position (Internal)
6. Position (External)
7. Speed (pulse)

Modify anytime, effective re-power

Modify OFF, effective ON

Modify anytime, effective immediately

Read-only

Modified

Communication status: on-line

In "Help" section from main menu you can find device manual for XINJE DS2 Series Servo, the software manual you're reading right now and the information about author of this software.