Digital temperature controller

INSTRUCTION MANUAL

Thank you for purchasing HANYOUNG product.

Please check whether the product is the exactly same as you ordered.

Before using the product, please read this instruction manual carefully.

Please keep this manual where you can view at any time

Safety information

Alerts declared in the manual are classified to Danger, Warning and Caution by their criticality

⚠ DANGER	DANGER indicates an imminently hazardous situation which, if not avoided, will result in death or serious injury
	WARNING indicates a potentially hazardous situation which, if not avoided, could result in death or serious injury
⚠ CAUTION	CAUTION indicates a potentially hazardous situation which, if not avoided, may result in minor or moderate injury

Danger

Do not touch or connect any undesirable conductive part to input-output terminal since there is a possibility of electric shock.

Warning

- Please install an appropriate protective circuit on the outside if malfunction or an incorrect operation may be a cause of leading to a serious accident.
- · Since this product does not have the power switch or a fuse, please install those separately on the outside. (Fuse rating : 250 V 0.5 A)
- To prevent damage or failure of this product, please supply the rated power voltage.
- To prevent electric shock or equipment failure, please do not turn on the power until completing wiring.
- Since this is not explosion-proof structure, please do not use in a place where combustible or explosive gas is around.
- Never disassemble, modify, or repair the product. There is a possibility of malfunction, electric shock, or a risk of fire.
- · Please turn off the power when mounting/dismounting of the product, This is a cause of electric shock, malfunction, or failure,
- . If the product is used with methods other than specified by the manufacturer, then it may lead to injury or property damage,
- . Since there is a possibility of electric shock, please use the product as mounted on a panel while the power is being supplied.
- If it is used with systems, machines and equipment that could lead to a risk of life or property damage, please implement safety devices and protections for both lives and the applications and plan for preventing accidents,

! Caution

- The contents of the instruction manual are subjective to change without prior notice,
- · Please make sure that the specification is the same as what you have ordered.
- · Please make sure that the product is not damaged during shipping.
- \bullet Please use this product in a place where the ambient operating temperature is 0 \sim 50 $^{\circ}$ C (40 $^{\circ}$ C max, closely installed) and the ambient operating humidity is 35 \sim 85 % R,H (without condensation).
- · Please use this product in a place where corrosive gas (such as harmful gas, ammonia, etc.) and flammable gas do not occur.
- Please use this product in a place where there is no direct vibration and a large physical impact to the product.
- . Please use this product in a place where there is no water, oil, chemicals, steam, dust, salt, iron or others (Contamination class 1 or 2).
- · Please do not wipe this product with organic solvents such as alcohol, benzene and others, (Please use mild detergent)
- · Please avoid places where excessive amounts of inductive interference and electrostatic and magnetic noise occur.
- · Please avoid places where heat accumulation occurs due to direct sunlight or radiant heat. • Please use this product in a place where the elevation is below 2,000 m.
- · Please make sure to inspect the product if exposed to water since there is a possibility of electric leakage or a risk of fire,
- · For thermocouple (TC) input, please use a prescribed compensation lead wire. (There is a temperature error if a general lead is used.)
- · For resistance temperature detector (RTD) input, please use a small resistance of lead wire and the 3 lead wires should have the same resistance, (There is a temperature error if the 3 lead wires do not have the same resistance,)
- · Please put the input signal wire away from the power lines and load lines to avoid the effect of inductive noise.
- The input signal wires and output signal wires should be separated from each other.
- If it is not possible, please use shielded wires for the input signal wires.
- · For thermocouple (TC), please use ungrounded sensors. (There is a possibility of malfunction of product by electric leakage if a grounded sensor is used.)
- · If there is a lot of noise from the power line, installing an insulated transformer or a noise filter is recommended. The noise filter should be grounded on the panel and the wire between the output of the noise filter and the power of the instrument should be as short as possible.
- It is effective against noise if making the power lines of the product the twisted pair wiring.
- · Please make sure the operation of the product before using since the product may not operate as it intends if the alarm function is not properly set.
- · When replacing the sensor, please turn off the power.
- In case of the high frequent operation such as proportional operation, please use an auxiliary relay since the life span of the output relay will be shortened if it connects to the load without the rated margin. In this case, SSR output is recommended.
 - * Electromagnetic switch: proportion cycle: set min. 20 sec
 - *SSR: proportion cycle: set min,1 sec
- · Please do not connect anything to the unused terminals.
- · Please connect wires properly after making sure the polarity of terminal,
- Please use a switch or breaker (IEC60947-1 or IEC60947-3 approved) when the product is mounted on a panel,
- · Please install a switch or break near the operator to facilitate its operation.
- If a switch or breaker is installed, please put a name plate that the power is off when the switch or breaker is activated,
- In order to use this product properly and safely, we recommend periodic maintenance.
- · Some parts of this product have limited expected life span and aged deterioration. . The warranty of this product (including accessories) is 1 year only when it is used for the purpose it was intended under normal condition,
- · When the power is being supplied there should be a preparation time for the contact output, Please use a delay relay together when it is used as a signal on the outside of interlock circuit or others.
- . When the user replaces with a spare unit due to product failure or other reason, please check the compatibility since the operation can be varied by the difference of setting parameters even though the model name and code are the same,
- Before using a temperature controller, there could be a temperature difference between PV of the temperature controller and the actual temperature so please operate the temperature controller after correcting the temperature difference appropriately.

HATIYOUTG NUX



HANYOUNGNUX CO.,LTD

1381-3, Juan-Dong, Nam-Gu Incheon, Korea, HEAD OFFICE

TEL: (82-32)876-4697 FAX: (82-32)876-4696 http://www.hynux.net

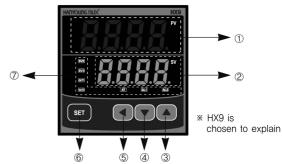
PT. HANYOUNG ELECTRONIC INDONESIA
Jl. Pinang blok F16, No.02 Delta Silikon III Cicau Cikarang Pusat. Bekasi Indonesia

INDONESIA FACTORY TEL: 62-21-8911-8120~4 FAX: 62-21-8911-8126

Suffix code

Model	Model Code			Description		
НХ				Multi-input and output digital	temperature controller	
	2			48(W) × 96(H) mm		
	3			96(W) × 48(H) mm		
Dimension	4			48(W) × 48(H) mm	P.I.D Auto-tuning	
Dilliension	7			72(W) × 72(H) mm		
	9			96(W) × 96(H) mm		
Control output 0			Normal (heating control)			
Control o	utput	1		Heating/cooling control (simultaneous control)		
111/0/0/0/0			0	None		
HX2/3/9	optioi	n	1	RS485 communication + Heater break alarm (H.B.A)		
			0	None		
HX7 opti	on		1	RS485 communication + D.I 2 contacts (SV2, SV3)		
	2		2	RS485 communication + Hea	ter break alarm (H.B.A)	
	0		0	None		
HX4 option 1		1	RS485 communication + D.I 1 contact (SV2)			
		2	RS485 communication + Heater break alarm (H.B.A)			

Part name and function



Number	Name	Description
1	Process value (PV)	Displays the process value in the operation mode.
2	Set value (SV)	Displays the set value in the operation mode
	■ Up key	Increases the set value or used to move between groups
3	Up key	and to change an option in a parameter in setting mode
<i>•</i>	Down key	Decreases the set value or used to move between groups
4	Down key	and to change an option in a parameter in setting mode
(5)	Shift key	Used to move the position of the digit
6	Set key	Sets (confirm) the set value, displays the output amount, or set an option in a parameter in setting mode and moves between the parameters in a group. By pressing for 3 seconds, it enters the display setting mode (setting mode) or returns to the operation mode
	SV2	Lights when SV2 is displayed
	SV3	Lights when SV3 is displayed
	Operation	OUT1 indicator
7	OUT2 Indicator	OUT2 indicator
	AT	Auto-tuning indicator
	AL1	Alarm 1 operation indicator
	AL2	Alarm 2 operation indicator

External Contact Input (D.I) Selection

3 predetermined set values (temperature values) could be changed with using ON/OFF of the external 2 contact inputs,

	External	OFF (contact input is not used)	ON (contact input is used)			
	input	No display	External contact input	SV2	SV3	
	contact		Set value 1 display (SV1)	OFF	OFF	
- 11	selection		Set value 2 display (SV2)	ON	OFF	
	(41.5)		Set value 3 display (SV3)	OFF	ON	

■ Control Output Composition

HX series is a multi-control-output temperature controller. It can have relay ON/OFF, SSR voltage pulse output, 4 - 20 mA current output as a control output by selecting an option in the parameter.

If the option is chosen like the below in the output parameter (aUE) in the output group (EaUE) of the normal temperature controller

- 0 : Relay ON/OFF control is as a control output.
- 1 : SSR output is as a control output.
- 2:4 20 mA d.c current output is as a control output.
- 3 : Relay PID control is as a control output,

(1) Normal type (heating control)

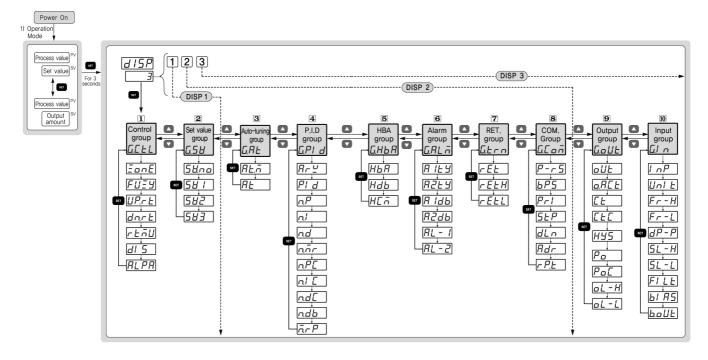
,	(, , , , , , , , , , , , , , , , , , ,								
Output code		OUT1(Heating)		OUT2		Default			
		Relay	SSR/SCR/RET	Relay	SSR/SCR/RET	Delault			
	0	Relay(ON/OFF)	-	AL2	RET				
Normal	1	_	SSR	(Alarm 2	(retransmission	1			
	2		SCR(4 - 20 mA)	output)	output)	'			
	3	Relay(PID)	_	output)	output)				

^{*} In normal type, retransmission output (RET.) is not available.

(2) Heating/cooling Type

Туре	Output		OUT1(Heating)	OL	JT2	Default
Type	code	Relay	SSR/SCR/RET	Relay	SSR/SCR/RET	Delault
	4		SSR			
	5		SCR (4 - 20 mA)	AL2	SSR	
	6	Relay	RET (retransmission output)	(Alarm 2		
Heating /	7		SSR		SCR	
Cooling	8		SCR (4 - 20 mA)	output)	(4 - 20 mA)	4
type	9	Relay	RET (retransmission output)		(4 - 20 IIIA)	
	10		SSR	Relay	RET	
	11		SCR(4 - 20 mA)	(control	(Retransmission	
	12	Relay		output)	output)	

Setting Mode



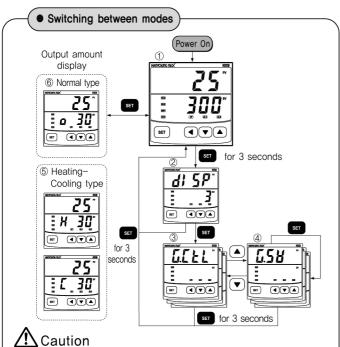
Input code for input type and range -

Input signal	Input code	Input type	Range (℃)	Accuracy	Note
	1	K *2	−200 ~ 1370		
	2	K *2	−199.9 ~ 999.9		
	3	J *2	−199.9 ~ 999.9	±0.5 % of F.S ±1digit	
	4	E *2	−199.9 ~ 999.9		• F.S is the measurable range
	5	T *2	−199.9 ~ 400.0		from the maximum to the minimum
Thermocouple	6	R *2	0 ~ 1700		for each range.
(T.C)	7	B *1	0 ~ 1800	±0.5 % of F.S ±1digit	Digit is the minimum display value
	8	S	0 ~ 1700	20.5 % Of 1.5 2 Taigit	*1 0 ~ 400°C range :
	9	L *2	−199.9 ~ 900.0	±0.5 % of F.S ±1digit	\pm 10 % of F,S \pm 1 digit
	10	N	−200 ~ 1300	±1.0 % of F.S ±1digit	*2 below 0 °C :
	11	U *2	−199.9 ~ 400.0		\pm 1.0 % of F.S \pm 1 digit
	12	W	0 ~ 2300		*3 -150.0 ∼ 150.0 °C range :
	13	Platinel II	0 ~ 1390		\pm 1.0 % of F.S \pm 1 digit
Resistance	20 💥	KPt100 Ω * 3	−199.9 ~ 500.0		*20 → kPt 100 Ω
temperature	21 💥	Pt100 Ω *3	−199.9 ~ 640.0		*21 → Pt 100 Q (IEC751)
detector (RTD)	22	Pt100 Ω	−200 ~ 640		
DC voltage	30	1 ~ 5 V d.c	1 ~ 5 V d.c		
(VDC/mVDC)	31	$0\sim 100~\text{mV}~\text{d.c}$	0 \sim 100 mV d.c	±0.5 % of F.S ±1digit	
DC current	30 Ж	4 - 20 mA d.c	When current input is used, please connect a 250 Ω 0.1% resistor to the input terminal.		

Operation Method -

■ When turn the power on after completing wiring

- (1) After the firmware version of the temperature controller appears for a short period of time, the operation mode is running like the number ① that process value (current temperature) and the set value are displayed.
- (2) In the number ①, if so button is pressed for 3 seconds, it enters d1 5 P display setting mode. It can be selected as DISP 1, DISP 2 and DISP 3 to limit displaying setting groups.



1 Control group -

	Symbol	Parameter	Option	Available condition	Default
ſ	-G.C.E.L.	Control group	Options for control mode	-	-
	EonE	Zone setting	OFF / ON	Always on	OFF
F	FUES	Fuzzy function setting	OFF / ON	PID control	OFF
SE		Initial temperature increase setting	OFF / EUS (0 \sim 100 %)	Always on	OFF
SE		Initial temperature decrease setting	OFF / EUS (0 \sim 100 %)	Always on	OFF
1 5	<u> ١٤ - ١</u>	Time for slope in ramp function	HOUR / MIN	Always on	HOUR
	d1 5	External contact input setting	OFF / ON	Always on	OFF
L	-RL PR	2 degrees of freedom gain setting	1 ~ 100 %	Always on	85

2 Set value (SV) setting group

			g g.cs.p		
Syn	nbol	Parameter	Option	Available condition	Default
⊢ [.5 <i>H</i>	Set value setting group	Options for set values	_	-
	11	Set value Number	1~3 (the chosen set value		1
	5 <u>8.0 o</u>	setting	is displayed and controlled)		1
5	B I	Set value 1 (SV1) setting	EU (0.0 ~ 100.0 %)	Always on	EU(0,0 %)
5	82	Set value 2 (SV2) setting	EU (0.0 ~ 100.0 %)	OII	EU(0,0 %)
45	83	Set value 3 (SV3) setting	EU (0.0 ~ 100.0 %)		EU(0.0 %)

3 Auto-tuning (AT) group -

Symbol	Parameter	Option	Available condition	Default			
→ G.R.Ł	Auto-tuning group	Options for auto-tuning (AT) group	_	-			
SET RL.	Auto-tuning type setting	Standard (STD) : 5 Ł d/ Low PV (LOW) : L a L	ABS	STD			
RE.	Auto-tuning start setting	OFF / 1 ~ 3 / # U L (AUTO)	ABS	OFF			

4 P.I.D group

	Symbol	Parameter	Option	Available condition	Default
	-GPI d	PID group	Options for P.I.D mode	-	-
	Ar <u>u</u>	ANTI RESET WIND-UP setting	Auto / 50.0 ~ 200.0 %	P.I.D control	100 %
	PId	PID group setting	0 / 1 ~ 3	Always on	0
	n.P	n. Proportional band (P)	0.1(H/C TYPE : 0.0) ~ 999.9 %	Selecting one of P.I.D group	5.0 %
SI	n.l	n, Integral time (I)	OFF / 1 \sim 6000 s	Always on	240 s
	n.d	n. Derivative time (D)	OFF / 1 ~ 6000 s	Always on	60 s
	תחר	n, Manual reset	−5.0 ~ 105.0 %	Integral time: OFF	50.0 %
	n.P.C	n, Proportional band (P) for cooling	0.0(ON/OFF control) / 0,1 ~ 999,9 %	heating · cooling	5.0 %
	n! [n. Integral time (I) for cooling	OFF / 1 ~ 6000 s	heating · cooling	240 s
	n.d.E	n, Derivative time (D) for cooling	OFF / 1 ~ 6000 s	heating · cooling	60 s
	ndb	n, hysteresis (dead band)	−100.0 ~ 50.0 %	heating · cooling	3.0 %
	LrP	n. Zone position setting	EU(0) < 1.RP < 2.RP < EU(100.0 %)	P.I.D group 1 or P.I.D group 2	EU (100,0 %)

5 Heater Break Alarm (HBA) group -

Symbol	Parameter	Option	Available condition	Default
→G.HЬR	Heater break alarm group	Options for HBA mode.	-	-
⊥нь́я	Current setting of HBA output	OFF / 1 ~ 50 A	HBA Option	OFF
Hdb	Hysteresis setting of HBA output	EUS (0.0 ~ 100.0 %)		EUS(0.5 %)
HEA	Current measurement	Only indicates current	"model name and	
	value of HBA output	measurement value (0 \sim 50 A)		

6 Alarm group ——

Symbol		Parameter	Option	Available condition	Default
→ <u>G.R.L. ⊼</u> Alarm group		Alarm group	Options for alarm mode	-	-
Я	Riby Alarm 1 type setting		OFF / 1 ~ 22	A1	1
<i>₽5</i> £3*		Alarm 2 type setting	Refer to "Alarm type and code"	Always on	2
SET A	ldЬ	Hysteresis (dead band) of alarm 1		Always on	EUS
Ra	?dЬ*	Hysteresis (dead band) of alarm 2	$\frac{1}{1}$ EUS(0.0 \sim 100.0 %) Always on		(0.5 %)
RL	Set value of alarm 1 PV alarm, deviation alarm:		Always on	EU(100.0 %)	
RL	2*	Set value of alarm 2	EU(-100.0 ~ 100.0 %)	Always Ull	EU(0,0 %)

7 Retransmission (RET) group -

Symbol	Parameter	Option	Available condition	Default
→ [j. Ł r n	RET. Group	Options for RET. Group	_	-
r E E	Retransmission type or power for sensor	Process value(PV) / set value (SV) / output amount (MV) / power for sensor (SPS)	RET. option	PV
- EEH	High limit of retransmission	T.C / RTD: FR-H ~ FR-L		EU(100,0 %)
	Low limit of	DC voltage: SL-H ~ SL-L	PV / SV	EU
<u>rEEL</u>	retransmission	But, RET.H > RET.L		(0.0 %)

8 Communication group –

;	Symbol	Parameter	Option	Available condition	Default
		Communication group	Options for communication mode,	-	-
			PC.LINK (code: 0)		
	P-c5	RS 485 / RS 422	PC.LINK SUM (code: 1)		0
		Protocol	MODBUS-ASCII(code: 2)		0
			MODBUS-RTU (code: 3)		
		Communication	2400 (code: 2), 4800 (code: 3),		
	<i>ЬР</i> 5		9600 (code: 4), 14400(code: 5),		4
SE		speed (b,F,S)	19600(code:6)	Comm.	
-	PrI	Parity Bit	NONE(code: 0),	Option	1
		Parity bit	EVEN(code: 1), ODD(code: 2)	Option	'
	5£P	Stop Bit	1bit (code : 1), 2bit (code : 2)		1
		Data length	7bit (code: 7), 8bit (code: 8)		8
	dLn.		(code 8 is not available for PC LINK)		0
	Rdr	Address	$1\sim 99$ but, max 31 units		1
			$0\sim$ 10, Response time = (processing		0
	⊢r P.Ł	Response time	time + response time) X 10 ms		U

9 Output group

Caution Please make sure to choose "input code" in "input code setting" of the input group first and then select "output code" in "output type setting" and other options in other groups. If other options are selected first and then input code is changed to other input code, the options in the other groups will be changed.

Symbol		Parameter	Option	Available condition	Default
→[i.oUE]		Output group	Options for output type and mode	_	_
0	ÚЕ	Output type setting	Refer to "control output composition"	Always on	(0 / 3)
0.	RCE	Output operation	REV: reverse, DIR: direct	Output code 0~3	REV
	Ė.	Cycle time	$1 \sim 1000 \text{ s}$	relay / S.S.R	30 s
	ĿĹ	Cycle time for cooling	$1 \sim 1000 \text{ s}$	Output code 4~12	30 s
H	¥5	Hysteresis for normal type	EUS $(0.0 \sim 100.0 \%)$	ON/OFF control	EUS(0,5 %)
SET		Hysteresis for heating-cooling type	0.0 ~ 10.0 %	Heating-cooling	0.5 %
			Normal : -5.0 \sim 105.0 %	Always on	0.0 %
	Po	OUT1 when input break	Heating-cooling: 0.0 \sim 105.0 %	Always On	0.0 %
	οE	Output amount of	0.0 ~ 105.0 %	Heating-	0.0 %
		OUT2 when input break	0,0 100,0 %	cooling	0.0 %
	□ L - H	High limit of output	Normal : OL-L + 1Digit~ 105.0 %	PID	100.0 %
	<u>L - H</u>	amount	Heating-cooling : 0.0 \sim 105.0 %	control	100,0 /6
	<u> </u>	Low limit of output	Normal : -0.5 % \sim OL-H-1Digit	PID	0.0 %
	L-L	amount	Heating-cooling : 0.0 \sim 105.0 %	control	100.0 %

10 Input group

,	Symbol	Parameter	Option	Available condition	Default
		Input group	Options for input type and input mode	_	-
	I oP	Input code setting	Input signal and	Always on	Code:
			measurable range code		00
	Un! E	Temperature unit setting	°C / °F	T.C or R.T.D	°C
	Fr-H	High limit setting	Within range (refer to "input code for input type and	Always on	1370
	Fr-L	Low limit setting	range") but, FR-H > FR-L	Always on	-200
SET		Decimal point position	Fixed for T.C or RTD / DC	Voltage input	
	dP-P	(voltage input)	voltage: 0~3 setting for decimal point position	(mV,V)	1
	5L - H	High limit of scale (voltage input)	-1999 ~ 9999 but, SL-H > SL-L	Voltage input	100.0
	5L-L	Low limit of scale (voltage input)	decimal point according to DP-P	(mV,V)	0.0
	FILE	Process value filter	OFF / 1 ~ 120 sec	Always on	OFF
	ы Я5	Process value bias (compensation)	EUS(-100.0 ~ 100.0 %)	Always on	EUS(0,0 %)
	-b.oUE	Operation after input break (burn-out)	OFF / UP / DOWN	Always on	UP

Alarm type and code

(Caution): In case of connecting in an inverse direction such as connecting a normally closed relay, the output is not delivered to the actuator even though the indicator is ON. Hysteresis-

$ \text{Hysteresis} \underbrace{\hspace{1.5cm}}_{\text{\bot}} (\triangle: \text{set value, } - \!\!\! \blacktriangle: - \text{ alarm set value, } \!\!\! \blacktriangle: \text{alarm set value)} $			
Code	Alarm type	Operation	
1	High absolute value (NO)		
2	Low absolute value (NO)		
3	High deviation value (NO)		
4	Low deviation value (NO)		
5	High deviation value (NC)		
6	Low deviation value (NC)		
7	High-Low deviation value		
8	High-Low deviation range		
9	High absolute value (NC)		
10	Low absolute value (NC)		
11	High absolute (NO, Hold)		
12	Low absolute (NO, Hold)		
13	High deviation (NO, Hold)		
14	Low deviation (NO, Hold)		
15	High deviation (NC, Hold)		
16	Low deviation (NC, Hold)		
17	High-Low deviation value (Hold)		
18	High-Low deviation range (Hold)		
19	High absolute value (NC, Hold)		
20	Low absolute value (NC, Hold)		
21	Heater break alarm 1 (HBA1)		

Function

■ Function Description

Function 1) Auto-tuning

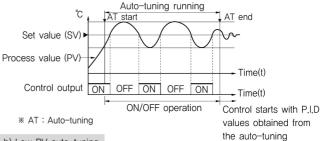
Auto-tuning is a function that the controller automatically measures the characteristic of the target system and calculates the optimal values for proportional band (P), integral time (I), and derivative time (D) and then set the optimal value for each P.I.D parameter. During auto-tuning, the control output is changed to ON/OFF control to get response from the target system, From the response, the most appropriate P,I,D values are obtained for the system. This is called Limit Cycle,

① Standard auto-tuning: This auto-tuning is based on the set value (SV).

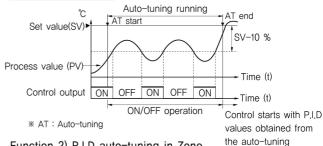
HX series has two types of auto-tuning: standard type and low PV type.

2 Low PV auto-tuning: This auto-tuning is based on the value 10 % lower than the set value (SV).

a) Standard auto-tuning

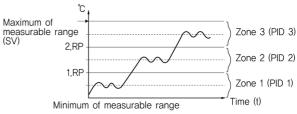


b) Low PV auto-tuning



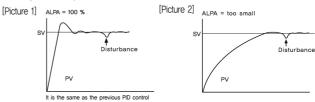
Function 2) P.I.D auto-tuning in Zone

Within the input range, 3 different P.I.D groups can be applied to each zone of 3. Since some systems have a wide range of temperature to control and the optimal P.I.D values are different for their temperature ranges, this function can be used to apply different optimal P.I.D values to their temperature ranges.



Function 3) 2 degrees of freedom P.I.D

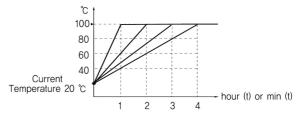
In order to get better response against disturbance in the steady state, there is usually a large overshoot in the transient state. To reduce this overshoot in the transient state, 2 degrees of freedom P.I.D control is used while obtaining good disturbance response in the steady state. The parameter "ALPA" is used to control the amount of overshoot,



* Note 1: If ALPA = 100 %, it is the same as the previous P.I.D control

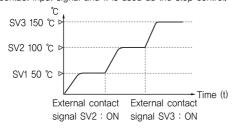
Function 4) Ramp function

This is the slope used to reach the set value (SV). The ramp function can be set in "control group" with setting the set value in "initial temperature increase" or "initial temperature decrease" and setting hour or min in "time for slope in ramp function. With this slope (= the desired value/ time) the current temperature reaches to the set value (SV).



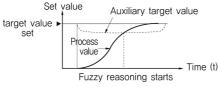
Function 5) External contact input

This function is used to select one of set values (SV1, SV2, SV3) by the external contact input signal and it is used as the step control.



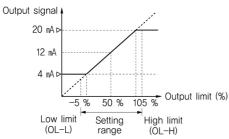
Function 6) Fuzzy calculation

Fuzzy calculation suppresses the overshoot.



Function 7) Output limit

This function is used to set the high limit and low limit as the operating range of the control output. The output limit (the high limit and low limit) can be set $-5 \sim 105$ % of the output amount,



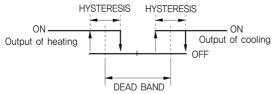
Function 8) Heater break alarm

- 1) This detects heater break and immediately turn on alarm.
- 2 Please use the current transformer (CT) designed by Hanyoung NUX.
- 3 The electric current value and alarm operating point (hysteresis) are set in "HBA group".
- 4 This cannot be used if phase control method (SCR output) is used by thyristor,

Function 9) Heating/cooling control

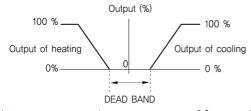
In heating/cooling control, it divides the PID computation result into two control signals and it outputs to each heating and cooling. The control method for each heating and cooling can be selected either PID control or ON/OFF control. Also, it is possible to choose one of the control outputs: relay output, SSR, and current output as the heating output and cooling output,

If both heating and cooling are controlled by ON/OFF control, the dead band (hysteresis) is shown as below.



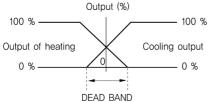
(ON/OFF control for heating/cooling)

The dead band of PID control for heating/cooling is shown as below.



 $\langle \text{PID control for heating/cooling: Dead band of "+" set value} \rangle$

Also, the dead band of "-" set value and the dead band of PID control for both heating and cooling are shown as below. At this time, there is an overlapped output from the both.



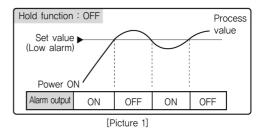
⟨PID control for heating/cooling: Dead band of "-" set value⟩

Function 10) Output during emergency

When there is A/D Error or input break (Burn-out), it stops the PID control output and then it outputs the preset value of output, (P_{Ω} parameter in output group)

Function 11) Hold function

Without hold function, Low limit alarm will be ON when increasing temperature after turning on the power. (Refer to picture 1) In order to not turn on the low limit alarm while the temperature is increasing, the hold function is used to not activate the low limit alarm from the point where the power is on to the point where goes over the low limit set value.



Hold function : ON

Process

Set value (Low alarm)

Power ON

Alarm output OFF OFF ON OFF

(Hold ON)

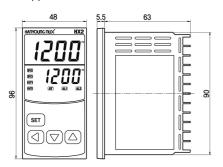
[Picture 2]

Specification

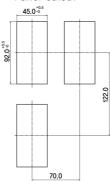
Power supply 100 - 240 V a.c (±10 %), 50/60 Hz				
	er consumption	6 W max, 10 VA max		
Type		Refer to "input code for input type and range"		
	Sampling cycle	62.5 ms		
	Accuracy	±0.5 % of F.S (refer to "input code for input type and range")		
		Within ±20 V d.c (VDC), within ±10 V d.c (TC, RTD)		
Input	Reference junction	Vitalit = 20 V d.0 (VBO), Within = 10 V d.0 (10, 1(10)		
	compensation accuracy	±3.5 ℃ (0 ~ 50 ℃)		
	Operation after input break	T.C: OFF, UP/DOWN RTD: UP		
	5.1	NO: 5 A 250 V a.c. 5 A 30 V d.c (resistive load)		
	Relay	NC: 3 A 250 V a.c, 1 A 30 V d.c (resistive load)		
Control	S.S.R	ON voltage: 12 V d.c min, OFF voltage: 0,1 V d.c max		
output	(voltage pulse)	Load resistance 600 Ω min		
	S.C.R	range: 4 - 20 mA (±5%), accuracy: ±0.2 mA		
	(current)	Load resistance 600 Ω max		
		range: 4 - 20 mA (±5%), accuracy: ±0.2 mA		
Retrar	smission output	Load resistance 600 Ω max		
А	larm output	5 A 250 V a.c, 5 A 30 V d.c (resistive load)		
С	ontact input	OFF resistance : 10 κρ min, ON resistance : 1 κρ max		
	Method	ON/OFF, P.I.D control		
Control	Output operation	Reverse operation, Direct operation		
	Anti-reset windup	Auto(A=0), 0.1 ~ 100.0 %		
	Standard	EIA RS485		
	Max connection unit	31 units (but, ADDRESS setting : 1 \sim 99)		
	Communication method	2 wire half duplex		
	Data transmission	asynchronous		
	Communication sequence	None		
	Communication distance	1.2 km max		
Interface	Communication Speed	2400, 4800, 9600, 14400, 19600 BPS (selectable by parameter)		
	Start bit	1 BIT		
	Data length	7 or 8 BIT		
	Parity bit	NONE, EVEN, ODD		
	Stop bit	1 or 2 BIT		
	Protocol	PC.LINK, PC.LINK SUM, MODBUS-ASCII, MODBUS-RTU		
	Response time	Processing time in receiving + (response time x 10 ms)		
2 degrees of freedom P.I.D		1 \sim 100% of proportional band		
Insulation resistance		20 Mp min (primary terminal - secondary terminal)		
Dielectric strength		2,300 V a.c, for 1 minute (primary terminal - secondary terminal)		
Operating	ambient temperature	$0\sim 50$ °C, (without condensation)		
Operatir	ng ambient humidity	35 \sim 85 % R.H (without condensation)		

HX2

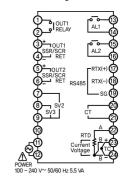




● Panel cutout

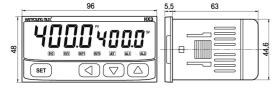


Connection Diagram

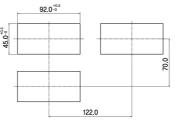


НХ3

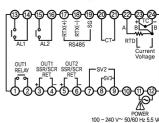
Appearance



Panel cutout

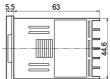


Connection Diagram

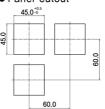


HX4

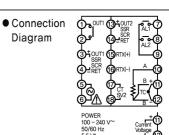




Panel cutout



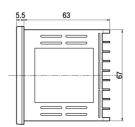
Diagram



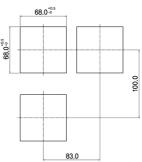
HX7

Appearance

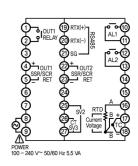




Panel cutout



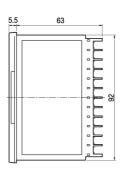
Connection Diagram

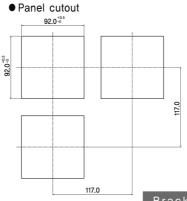


HX9

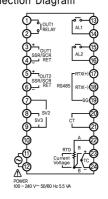
Appearance



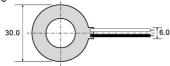


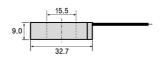


Connection Diagram



Appearance





Bracket

